# IS42S16400J IS45S16400J



# 1 Meg Bits x 16 Bits x 4 Banks (64-MBIT) SYNCHRONOUS DYNAMIC RAM

#### **FEBRUARY 2022**

#### **FEATURES**

- Clock frequency: 200, 166, 143, 133 MHz
- Fully synchronous; all signals referenced to a positive clock edge
- Internal bank for hiding row access/precharge
- Single 3.3V power supply
- · LVTTL interface
- Programmable burst length
   (1, 2, 4, 8, full page)
- Programmable burst sequence: Sequential/Interleave
- · Self refresh modes
- Auto refresh (CBR)
- 4096 refresh cycles every 64 ms (Com, Ind, A1 grade) or 16ms (A2 grade)
- · Random column address every clock cycle
- Programmable CAS latency (2, 3 clocks)
- Burst read/write and burst read/single write operations capability
- Burst termination by burst stop and precharge command

#### **OPTIONS**

- Package:
   54-pin TSOP II
   54-ball TF-BGA (8mm x 8mm)
   60-ball TF-BGA (10.1mm x 6.4mm)
- Operating Temperature Range Commercial (0°C to +70°C) Industrial (-40°C to +85°C) Automotive Grade A1 (-40°C to +85°C) Automotive Grade A2 (-40°C to +105°C)

#### OVERVIEW

*ISSI*'s 64Mb Synchronous DRAM is organized as 1,048,576 bits x 16-bit x 4-bank for improved performance. The synchronous DRAMs achieve high-speed data transfer using pipeline architecture. All inputs and outputs signals refer to the rising edge of the clock input.

#### **KEY TIMING PARAMETERS**

Parameter	-5	-6	-7	Unit
Clk Cycle Time				
CAS Latency = 3	5	6	7	ns
CAS Latency = 2	7.5	7.5	7.5	ns
Clk Frequency				
CAS Latency = 3	200	166	143	Mhz
CAS Latency = 2	133	133	133	Mhz
Access Time from Clock				
CAS Latency = 3	4.8	5.4	5.4	ns
CAS Latency = 2	5.4	5.4	5.4	ns

# **ADDRESS TABLE**

Parameter	4M x 16		
Configuration	1M x 16 x 4 banks		
Refresh Count			
Com./Ind.	4K/64ms		
A1	4K/64ms		
A2	4K/16ms		
Row Addresses	A0-A11		
Column Addresses	A0-A7		
Bank Address Pins	BA0, BA1		
Auto Precharge Pins	A10/AP		

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a.) the risk of injury or damage has been minimized;

b.) the user assume all such risks; and

c.) potential liability of Integrated Silicon Solution, Inc is adequately protected under the circumstances



#### GENERAL DESCRIPTION

The 64Mb SDRAM is a high speed CMOS, dynamic random-access memory designed to operate in 3.3V memory systems containing 67,108,864 bits. Internally configured as a quad-bank DRAM with a synchronous interface. Each 16,777,216-bit bank is organized as 4,096 rows by 256 columns by 16 bits.

The 64Mb SDRAM includes an AUTO REFRESH MODE, and a power-saving, power-down mode. All signals are registered on the positive edge of the clock signal, CLK. All inputs and outputs are LVTTL compatible.

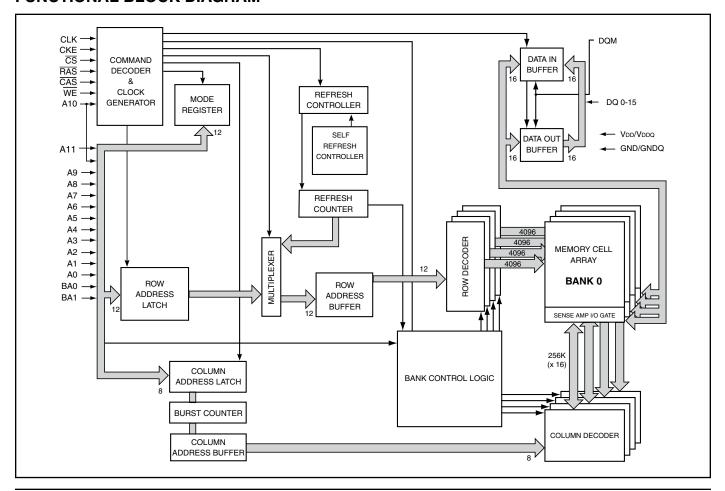
The 64Mb SDRAM has the ability to synchronously burst data at a high data rate with automatic column-address generation, the ability to interleave between internal banks to hide precharge time and the capability to randomly change column addresses on each clock cycle during burst access.

A self-timed row precharge initiated at the end of the burst sequence is available with the AUTO PRECHARGE function enabled. Precharge one bank while accessing one of the other three banks will hide the precharge cycles and provide seamless, high-speed, random-access operation.

SDRAM read and write accesses are burst oriented starting at a selected location and continuing for a programmed number of locations in a programmed sequence. The registration of an ACTIVE command begins accesses, followed by a READ or WRITE command. The ACTIVE command in conjunction with address bits registered are used to select the bank and row to be accessed (BAO, BA1 select the bank; A0-A11 select the row). The READ or WRITE commands in conjunction with address bits registered are used to select the starting column location for the burst access.

Programmable READ or WRITE burst lengths consist of 1, 2, 4 and 8 locations, or full page, with a burst terminate option.

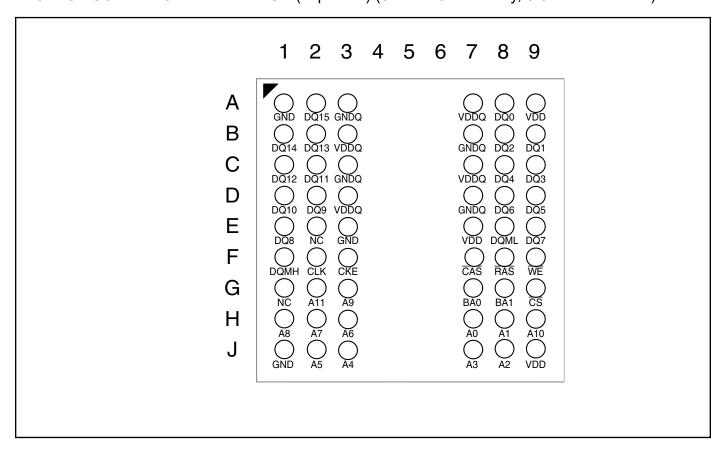
#### **FUNCTIONAL BLOCK DIAGRAM**





## **PIN CONFIGURATION**

PACKAGE CODE: B 54 BALL TF-BGA (Top View) (8 mm x 8 mm Body, 0.8 mm Ball Pitch)



## **PIN DESCRIPTIONS**

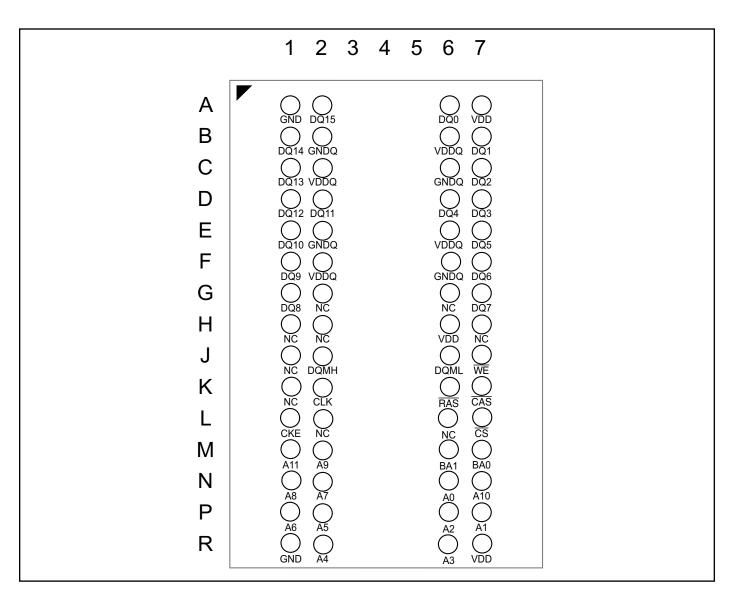
A0-A11	Row Address Input
A0-A7	Column Address Input
BA0, BA1	Bank Select Addresses
DQ0 to DQ15	Data I/O
CLK	System Clock Input
CKE	Clock Enable
<del>CS</del>	Chip Select
RAS	Row Address Strobe Command
CAS	Column Address Strobe Command

WE	Write Enable
DQML, DQMH	x16 Input/Output Mask
VDD	Power
GND	Ground
VDDQ	Power Supply for I/O Pin
GNDQ	Ground for I/O Pin
NC	No Connection



## **PIN CONFIGURATION**

PACKAGE CODE: B2 60 BALL TF-BGA (Top View) (10.1 mm x 6.4 mm Body, 0.65 mm Ball Pitch)



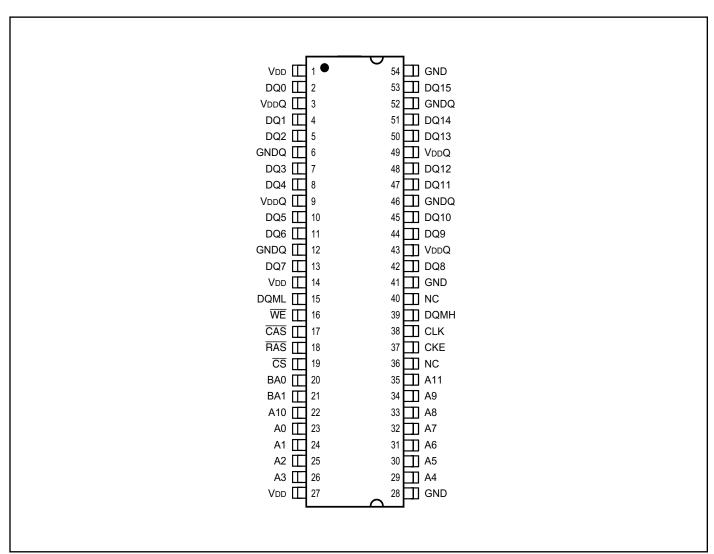
# PIN DESCRIPTIONS

A0-A11	Row Address Input
A0-A7	Column Address Input
BA0, BA1	Bank Select Addresses
DQ0 to DQ15	Data I/O
CLK	System Clock Input
CKE	Clock Enable
<del>CS</del>	Chip Select
RAS	Row Address Strobe Command
CAS	Column Address Strobe Command

WE	Write Enable
DQML, DQMH	x16 Input/Output Mask
V <sub>DD</sub>	Power
GND	Ground
VDDQ	Power Supply for I/O Pin
GNDQ	Ground for I/O Pin
NC	No Connection



# PIN CONFIGURATIONS 54 pin TSOP - Type II



# **PIN DESCRIPTIONS**

A0-A11	Row Address Input
A0-A7	Column Address Input
BA0, BA1	Bank Select Address
DQ0 to DQ15	Data I/O
CLK	System Clock Input
CKE	Clock Enable
CS	Chip Select
RAS	Row Address Strobe Command
CAS	Column Address Strobe Command

DQML x16 Lower Byte, Input/Output Mask  DQMH x16 Upper Byte, Input/Output Mask  VDD Power  GND Ground
V <sub>DD</sub> Power
GND Ground
and around
VDDQ Power Supply for I/O Pin
GNDQ Ground for I/O Pin
NC No Connection



# **PIN FUNCTIONS**

Symbol	TSOP Pin No.	Type	Function
A0-A11	23 to 26	Input Pin	Address Inputs: A0-A11 are sampled during the ACTIVE
	29 to 34		command (row-address A0-A11) and READ/WRITE command (A0-A7
	22, 35		with A10 defining auto precharge) to select one location out of the memory array in the respective bank. A10 is sampled during a PRECHARGE command to determine if all banks are to be precharged (A10 HIGH) or bank selected by BA0, BA1 (LOW). The address inputs also provide the op-code during a LOAD MODE REGISTER command.
BA0, BA1	20, 21	Input Pin	Bank Select Address: BA0 and BA1 defines which bank the ACTIVE, READ, WRITE or PRECHARGE command is being applied.
CAS	17	Input Pin	$\overline{\text{CAS}}$ , in conjunction with the $\overline{\text{RAS}}$ and $\overline{\text{WE}}$ , forms the device command. See the "Command Truth Table" for details on device commands.
CKE	37	Input Pin	The CKE input determines whether the CLK input is enabled. The next rising edge of the CLK signal will be valid when is CKE HIGH and invalid when LOW. When CKE is LOW, the device will be in either power-down mode, clock suspend mode, or self refresh mode. CKE is an asynchronous input.
CLK	38	Input Pin	CLK is the master clock input for this device. Except for CKE, all inputs to this device are acquired in synchronization with the rising edge of this pin.
CS	19	Input Pin	The $\overline{\text{CS}}$ input determines whether command input is enabled within the device. Command input is enabled when $\overline{\text{CS}}$ is LOW, and disabled with $\overline{\text{CS}}$ is HIGH. The device remains in the previous state when $\overline{\text{CS}}$ is HIGH.
DQ0 to	2, 4, 5, 7, 8, 10,	DQ Pin	DQ0 to DQ15 are I/O pins. I/O through these pins can be controlled in byte units
DQ15	11,13, 42, 44, 45, 47, 48, 50, 51, 53		using the DQML and DQMH pins.
DQML,	15, 39	Input Pin	DQML and DQMH control the lower and upper bytes of the I/O buffers. In read
DQMH			mode, DQML and DQMH control the output buffer. When DQML or DQMH is LOW, the corresponding buffer byte is enabled, and when HIGH, disabled. The outputs go to the HIGH impedance state when DQML/DQMH is HIGH. This function corresponds to $\overline{\text{OE}}$ in conventional DRAMs. In write mode, DQML and DQMH control the input buffer. When DQML or DQMH is LOW, the corresponding buffer byte is enabled, and data can be written to the device. When DQML or DQMH is HIGH, input data is masked and cannot be written to the device.
RAS	18	Input Pin	$\overline{RAS}$ , in conjunction with $\overline{CAS}$ and $\overline{WE}$ , forms the device command. See the "Command Truth Table" item for details on device commands.
WE	16	Input Pin	WE, in conjunction with RAS and CAS, forms the device command. See the "Command Truth Table" item for details on device commands.
VDDQ	3, 9, 43, 49	Power Supply Pin	VDDQ is the output buffer power supply.
V <sub>DD</sub>	1, 14, 27	Power Supply Pin	V <sub>DD</sub> is the device internal power supply.
GNDa	6, 12, 46, 52	Power Supply Pin	GNDa is the output buffer ground.
GND	28, 41, 54	Power Supply Pin	GND is the device internal ground.



#### **READ**

The READ command selects the bank from BA0, BA1 inputs and starts a burst read access to an active row. Inputs A0-A7 provides the starting column location. When A10 is HIGH, this command functions as an AUTO PRECHARGE command. When the auto precharge is selected, the row being accessed will be precharged at the end of the READ burst. The row will remain open for subsequent accesses when AUTO PRECHARGE is not selected. DQ's read data is subject to the logic level on the DQM inputs two clocks earlier. When a given DQM signal was registered HIGH, the corresponding DQ's will be High-Z two clocks later. DQ's will provide valid data when the DQM signal was registered LOW.

#### WRITE

A burst write access to an active row is initiated with the WRITE command. BA0, BA1 inputs selects the bank, and the starting column location is provided by inputs A0-A7. Whether or not AUTO-PRECHARGE is used is determined by A10.

The row being accessed will be precharged at the end of the WRITE burst, if AUTO PRECHARGE is selected. If AUTO PRECHARGE is not selected, the row will remain open for subsequent accesses.

A memory array is written with corresponding input data on DQ's and DQM input logic level appearing at the same time. Data will be written to memory when DQM signal is LOW. When DQM is HIGH, the corresponding data inputs will be ignored, and a WRITE will not be executed to that byte/column location.

#### **PRECHARGE**

The PRECHARGE command is used to deactivate the open row in a particular bank or the open row in all banks. BA0, BA1 can be used to select which bank is precharged or they are treated as "Don't Care". A10 determines whether one or all banks are precharged. After executing this command, the next command for the selected bank(s) is executed after passage of the period  $t_{\rm RP}$  which is the period required for bank precharging. Once a bank has been precharged, it is in the idle state and must be activated prior to any READ or WRITE commands being issued to that bank.

#### **AUTO PRECHARGE**

The AUTO PRECHARGE function ensures that the precharge is initiated at the earliest valid stage within a burst. This function allows for individual-bank precharge without requiring an explicit command. A10 can be used to enable the AUTO PRECHARGE function in conjunction with a specific READ or WRITE command. For each individual READ or WRITE command, auto precharge is either enabled or disabled. AUTO PRECHARGE does not

apply except in full-page burst mode. Upon completion of the READ or WRITE burst, a precharge of the bank/row that is addressed is automatically performed.

### **AUTO REFRESH COMMAND**

This command executes the AUTO REFRESH operation. The row address and bank to be refreshed are automatically generated during this operation. The stipulated period (tRc) is required for a single refresh operation, and no other commands can be executed during this period. This command is executed at least 4096 times every TREF. During an AUTO REFRESH command, address bits are "Don't Care". This command corresponds to CBR Auto-refresh.

#### **SELF REFRESH**

During the SELF REFRESH operation, the row address to be refreshed, the bank, and the refresh interval are generated automatically internally. SELF REFRESH can be used to retain data in the SDRAM without external clocking, even if the rest of the system is powered down. The SELF REFRESH operation is started by dropping the CKE pin from HIGH to LOW. During the SELF REFRESH operation all other inputs to the SDRAM become "Don't Care". The device must remain in self refresh mode for a minimum period equal to tras or may remain in self refresh mode for an indefinite period beyond that. The SELF-REFRESH operation continues as long as the CKE pin remains LOW and there is no need for external control of any other pins. The next command cannot be executed until the device internal recovery period (tRC) has elapsed. Once CKE goes HIGH, the NOP command must be issued (minimum of two clocks) to provide time for the completion of any internal refresh in progress. After the self-refresh, since it is impossible to determine the address of the last row to be refreshed, an AUTO-REFRESH should immediately be performed for all addresses.

#### **BURST TERMINATE**

The BURST TERMINATE command forcibly terminates the burst read and write operations by truncating either fixed-length or full-page bursts and the most recently registered READ or WRITE command prior to the BURST TERMINATE.

#### **COMMAND INHIBIT**

COMMAND INHIBIT prevents new commands from being executed. Operations in progress are not affected, apart from whether the CLK signal is enabled

#### **NO OPERATION**

When  $\overline{\text{CS}}$  is low, the NOP command prevents unwanted commands from being registered during idle or wait states



## **LOAD MODE REGISTER**

During the LOAD MODE REGISTER command the mode register is loaded from A0-A11. This command can only be issued when all banks are idle.

# **ACTIVE COMMAND**

When the ACTIVE COMMAND is activated, BA0, BA1 inputs selects a bank to be accessed, and the address inputs on A0-A11 selects the row. Until a PRECHARGE command is issued to the bank, the row remains open for accesses.



# TRUTH TABLE - COMMANDS AND DQM OPERATION(1)

FUNCTION	CS	RAS	CAS	WE	DQM	ADDR	DQs
COMMAND INHIBIT (NOP)	Н	Χ	Χ	Χ	Χ	Χ	Х
NO OPERATION (NOP)	L	Н	Н	Н	Χ	Χ	Χ
ACTIVE (Select bank and activate row)(3)	L	L	Н	Н	Χ	Bank/Row	Χ
READ (Select bank/column, start READ burst)(4)	L	Н	L	Н	L/H <sup>(8)</sup>	Bank/Col	Χ
WRITE (Select bank/column, start WRITE burst)(4)	L	Н	L	L	L/H <sup>(8)</sup>	Bank/Col	Valid
BURST TERMINATE	L	Н	Н	L	Χ	Χ	Active
PRECHARGE (Deactivate row in bank or banks)(5)	L	L	Н	L	Χ	Code	Χ
AUTO REFRESH or SELF REFRESH <sup>(6,7)</sup> (Enter self refresh mode)	L	L	L	Н	Χ	Х	Х
LOAD MODE REGISTER(2)	L	L	L	L	Χ	Op-Code	Χ
Write Enable/Output Enable(8)	_			_	Ĺ	_	Active
Write Inhibit/Output High-Z <sup>(8)</sup>	_			_	Н	_	High-Z

#### NOTES:

- 1. CKE is HIGH for all commands except SELF REFRESH.
- 2. A0-A11 define the op-code written to the mode register.
- 3. A0-A11 provide row address, and BA0, BA1 determine which bank is made active.
- 4. A0-A7 (x16) provide column address; A10 HIGH enables the auto precharge feature (nonpersistent), while A10 LOW disables auto precharge; BA0, BA1 determine which bank is being read from or written to.
- 5. A10 LOW: BAO, BA1 determine the bank being precharged. A10 HIGH: All banks precharged and BAO, BA1 are "Don't Care."
- 6. AUTO REFRESH if CKE is HIGH, SELF REFRESH if CKE is LOW.
- 7. Internal refresh counter controls row addressing; all inputs and I/Os are "Don't Care" except for CKE.
- 8. Activates or deactivates the DQs during WRITEs (zero-clock delay) and READs (two-clock delay).



### TRUTH TABLE - CKE (1-4)

CURRENT STATE	COMMANDn ACTIONn		CKEn-1	CKEn
Power-Down	X	Maintain Power-Down		L
Self Refresh	X	Maintain Self Refresh	L	L
Clock Suspend	X	Maintain Clock Suspend	L	L
Power-Down <sup>(5)</sup>	COMMAND INHIBIT or NOP	Exit Power-Down	L	Н
Self Refresh <sup>(6)</sup>	COMMAND INHIBIT or NOP	Exit Self Refresh	L	Н
Clock Suspend(7)	X	Exit Clock Suspend	L	Н
All Banks Idle	COMMAND INHIBIT or NOP	Power-Down Entry	Н	L
All Banks Idle	AUTO REFRESH	Self Refresh Entry	Н	L
Reading or Writing	VALID	Clock Suspend Entry	Н	L
	See TRUTH TABLE - CURRENT STATE BANK n, COMMAND TO BANK n			

#### NOTES:

- 1. CKEn is the logic state of CKE at clock edge n; CKEn-1 was the state of CKE at the previous clock edge.
- 2. Current state is the state of the SDRAM immediately prior to clock edge *n*.
- 3. COMMANDn is the command registered at clock edge *n*, and ACTONn is a result of COMMANDn.
- 4. All states and sequences not shown are illegal or reserved.
- 5. Exiting power-down at clock edge *n* will put the device in the all banks idle state in time for clock edge *n+1* (provided that toks is met).
- 6. Exiting self refresh at clock edge *n* will put the device in all banks idle state once txsR is met. COMMAND INHIBIT or NOP commands should be issued on clock edges occurring during the txsR period. A minimum of two NOP commands must be sent during txsR period.
- After exiting clock suspend at clock edge n, the device will resume operation and recognize the next command at clock edge n+1.

TRUTH TABLE – CURRENT STATE BANK n. COMMAND TO BANK  $n^{(1-6)}$ 

CURRENT STATE	COMMAND (ACTION)	$\overline{CS}$	$\overline{RAS}$	$\overline{CAS}$	WE
Any	COMMAND INHIBIT (NOP/Continue previous operation)	Н	Х	Х	Х
	NO OPERATION (NOP/Continue previous operation)	L	Н	Н	Н
Idle	ACTIVE (Select and activate row)	L	L	Н	Н
	AUTO REFRESH <sup>(7)</sup>	L	L	L	Н
	LOAD MODE REGISTER <sup>(7)</sup>	L	L	L	L
	PRECHARGE <sup>(11)</sup>	L	L	Н	L
Row Active	READ (Select column and start READ burst) <sup>(10)</sup>	L	Н	L	Н
	WRITE (Select column and start WRITE burst)(10)	L	Н	L	L
	PRECHARGE (Deactivate row in bank or banks)(8)	L	L	Н	L
Read	READ (Select column and start new READ burst) <sup>(10)</sup>	L	Н	L	Н
(Auto	WRITE (Select column and start WRITE burst)(10)	L	Н	L	L
Precharge	PRECHARGE (Truncate READ burst, start PRECHARGE)(8)	L	L	Н	L
Disabled)	BURST TERMINATE <sup>(9)</sup>	L	Н	Н	L
Write	READ (Select column and start READ burst) <sup>(10)</sup>	L	Н	L	Н
(Auto	WRITE (Select column and start new WRITE burst)(10)	L	Н	L	L
Precharge	PRECHARGE (Truncate WRITE burst, start PRECHARGE)(8)	L	L	Н	L
Disabled)	BURST TERMINATE <sup>(9)</sup>	L	Н	Н	L

#### NOTE:

- 1. This table applies when CKE n-1 was HIGH and CKE n is HIGH (see Truth Table CKE) and after txsR has been met (if the previous state was SELF REFRESH).
- 2. This table is bank-specific, except where noted; i.e., the current state is for a specific bank and the commands shown are those allowed to be issued to that bank when in that state. Exceptions are covered in the notes below.



- 3. Current state definitions:
  - Idle: The bank has been precharged, and tRP has been met.
  - Row Active: A row in the bank has been activated, and tRCD has been met. No data bursts/accesses and no register accesses are in progress.
    - Read: A READ burst has been initiated, with auto precharge disabled, and has not yet terminated or been terminated.
    - Write: A WRITE burst has been initiated, with auto precharge disabled, and has not yet terminated or been terminated.
- 4. The following states must not be interrupted by a command issued to the same bank. COMMAND INHIBIT or NOP commands, or allowable commands to the other bank should be issued on any clock edge occurring during these states. Allowable commands to the other bank are determined by its current state and CURRENT STATE BANK n truth tables.
  - Precharging: Starts with registration of a PRECHARGE command and ends when the is met. Once the is met, the bank will be in the idle state.
  - Row Activating: Starts with registration of an ACTIVE command and ends when tRCD is met. Once tRCD is met, the bank will be in the row active state.

Read w/Auto

Precharge Enabled: Starts with registration of a READ command with auto precharge enabled and ends when the has been met. Once the is met, the bank will be in the idle state.

Write w/Auto

- Precharge Enabled: Starts with registration of a WRITE command with auto precharge enabled and ends when the has been met. Once the is met, the bank will be in the idle state.
- 5. The following states must not be interrupted by any executable command; COMMAND INHIBIT or NOP commands must be applied on each positive clock edge during these states.
  - Refreshing: Starts with registration of an AUTO REFRESH command and ends when the is met. Once the is met, the SDRAM will be in the all banks idle state.

Accessing Mode

- Register: Starts with registration of a LOAD MODE REGISTER command and ends when tmrd has been met. Once tmrd is met, the SDRAM will be in the all banks idle state.
- Precharging All: Starts with registration of a PRECHARGE ALL command and ends when the is met. Once the is met, all banks will be in the idle state.
- 6. All states and sequences not shown are illegal or reserved.
- 7. Not bank-specific; requires that all banks are idle.
- 8. May or may not be bank-specific; if all banks are to be precharged, all must be in a valid state for precharging.
- 9. Not bank-specific; BURST TERMINATE affects the most recent READ or WRITE burst, regardless of bank.
- 10. READs or WRITEs listed in the Command (Action) column include READs or WRITEs with auto precharge enabled and READs or WRITEs with auto precharge disabled.
- 11. Does not affect the state of the bank and acts as a NOP to that bank.



TRUTH TABLE - CURRENT STATE BANK n, COMMAND TO BANK m (1-6)

CURRENT STATE	COMMAND (ACTION)	CS	RAS	CAS	WE
Any	COMMAND INHIBIT (NOP/Continue previous operation)	Н	Х	Х	Х
	NO OPERATION (NOP/Continue previous operation)	L	Н	Н	Н
Idle	Any Command Otherwise Allowed to Bank m	Х	Χ	Χ	Χ
Row	ACTIVE (Select and activate row)	L	L	Н	Н
Activating,	READ (Select column and start READ burst) <sup>(7)</sup>	L	Н	L	Н
Active, or	WRITE (Select column and start WRITE burst)(7)	L	Н	L	L
Precharging	PRECHARGE	L	L	Н	L
Read	ACTIVE (Select and activate row)	L	L	Н	Н
(Auto	READ (Select column and start new READ burst) <sup>(7,10)</sup>	L	Н	L	Н
Precharge	WRITE (Select column and start WRITE burst)(7,11)	L	Н	L	L
Disabled)	PRECHARGE <sup>(9)</sup>	L	L	Н	L
Write	ACTIVE (Select and activate row)	L	L	Н	Н
(Auto	READ (Select column and start READ burst) <sup>(7,12)</sup>	L	Н	L	Н
Precharge	WRITE (Select column and start new WRITE burst)(7,13)	L	Н	L	L
Disabled)	PRECHARGE <sup>(9)</sup>	L	L	Н	L
Read	ACTIVE (Select and activate row)	L	L	Н	Н
(With Auto	READ (Select column and start new READ burst) <sup>(7,8,14)</sup>	L	Н	L	Н
Precharge)	WRITE (Select column and start WRITE burst)(7,8,15)	L	Н	L	L
	PRECHARGE <sup>(9)</sup>	L	L	Н	L
Write	ACTIVE (Select and activate row)	L	L	Н	Н
(With Auto	READ (Select column and start READ burst) <sup>(7,8,16)</sup>	L	Н	L	Н
Precharge)	WRITE (Select column and start new WRITE burst)(7,8,17)	L	Н	L	L
	PRECHARGE <sup>(9)</sup>	L	L	Н	L

#### NOTE:

- 1. This table applies when CKE n-1 was HIGH and CKE n is HIGH (Truth Table CKE) and after txsR has been met (if the previous state was self refresh).
- 2. This table describes alternate bank operation, except where noted; i.e., the current state is for bank n and the commands shown are those allowed to be issued to bank m (assuming that bank m is in such a state that the given command is allowable). Exceptions are covered in the notes below.
- 3. Current state definitions:
  - Idle: The bank has been precharged, and tRP has been met.
  - Row Active: A row in the bank has been activated, and tRCD has been met. No data bursts/accesses and no register accesses are in progress.
    - Read: A READ burst has been initiated, with auto precharge disabled, and has not yet terminated or been terminated.
    - Write: A WRITE burst has been initiated, with auto precharge disabled, and has not yet terminated or been terminated.

Read w/Auto

Precharge Enabled: Starts with registration of a READ command with auto precharge enabled, and ends when the has been met. Once the is met, the bank will be in the idle state.

Write w/Auto

Precharge Enabled: Starts with registration of a WRITE command with auto precharge enabled, and ends when the has been met. Once the is met, the bank will be in the idle state.

- 4. AUTO REFRESH, SELF REFRESH and LOAD MODE REGISTER commands may only be issued when all banks are idle.
- 5. A BURST TERMINATE command cannot be issued to another bank; it applies to the bank represented by the current state only.
- 6. All states and sequences not shown are illegal or reserved.
- 7. READs or WRITEs to bank m listed in the Command (Action) column include READs or WRITEs with auto precharge enabled and READs or WRITEs with auto precharge disabled.

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- 8. CONCURRENT AUTO PRECHARGE: Bank n will initiate the AUTO PRECHARGE command when its burst has been interrupted by bank m's burst.
- 9. Burst in bank n continues as initiated.
- 10. For a READ without auto precharge interrupted by a READ (with or without auto precharge), the READ to bank m will interrupt the READ on bank n, CAS latency later (Consecutive READ Bursts).
- 11. For a READ without auto precharge interrupted by a WRITE (with or without auto precharge), the WRITE to bank m will interrupt the READ on bank n when registered (READ to WRITE). DQM should be used one clock prior to the WRITE command to prevent bus contention.
- 12. For a WRITE without auto precharge interrupted by a READ (with or without auto precharge), the READ to bank m will interrupt the WRITE on bank n when registered (WRITE to READ), with the data-out appearing CAS latency later. The last valid WRITE to bank n will be data-in registered one clock prior to the READ to bank m.
- 13. For a WRITE without auto precharge interrupted by a WRITE (with or without auto precharge), the WRITE to bank m will interrupt the WRITE on bank n when registered (WRITE to WRITE). The last valid WRITE to bank n will be data-in registered one clock prior to the READ to bank m.
- 14. For a READ with auto precharge interrupted by a READ (with or without auto precharge), the READ to bank m will interrupt the READ on bank n, CAS latency later. The PRECHARGE to bank n will begin when the READ to bank m is registered (Fig CAP 1).
- 15. For a READ with auto precharge interrupted by a WRITE (with or without auto precharge), the WRITE to bank m will interrupt the READ on bank n when registered. DQM should be used two clocks prior to the WRITE command to prevent bus contention. The PRECHARGE to bank n will begin when the WRITE to bank m is registered (Fig CAP 2).
- 16. For a WRITE with auto precharge interrupted by a READ (with or without auto precharge), the READ to bank m will interrupt the WRITE on bank n when registered, with the data-out appearing CAS latency later. The PRECHARGE to bank n will begin after twn is met, where twn begins when the READ to bank m is registered. The last valid WRITE to bank n will be data-in registered one clock prior to the READ to bank m (Fig CAP 3).
- 17. For a WRITE with auto precharge interrupted by a WRITE (with or without auto precharge), the WRITE to bank m will interrupt the WRITE on bank n when registered. The PRECHARGE to bank n will begin after two is met, where t WR begins when the WRITE to bank m is registered. The last valid WRITE to bank n will be data registered one clock prior to the WRITE to bank m (Fig CAP 4).



#### ABSOLUTE MAXIMUM RATINGS(1)

Symbol	Parameters		Rating	Unit
VDD MAX	Maximum Supply Voltage		-1.0 to +4.6	V
VDDQ MAX	Maximum Supply Voltage for	Output Buffer	-1.0 to +4.6	V
VIN	Input Voltage	-1.0 to VDDQ + 0.5	V	
Vouт	Output Voltage	-1.0 to VDDQ + 0.5	V	
PD MAX	Allowable Power Dissipation	1	W	
Ics	Output Shorted Current		50	mA
Topr	Operating Temperature	Com.	0 to +70	°C
		Ind.	-40 to +85	°C
		A1	-40 to +85	°C
		A2	-40 to +105	°C
Тѕтс	Storage Temperature		-65 to +150	°C

#### DC RECOMMENDED OPERATING CONDITIONS(2)

(At TA = 0 to  $+70^{\circ}$ C for commercial grade. TA = -40 to  $+85^{\circ}$ C for industrial and A1 grade. TA = -40 to  $+105^{\circ}$ C for A2 grade)

Symbol	Parameter	Min.	Тур.	Max.	Unit
Vdd, Vddq	Supply Voltage	3.0	3.3	3.6	V
VIH	Input High Voltage(3)	2.0	_	VDD + 0.3	V
VIL	Input Low Voltage(4)	-0.3	_	+0.8	V

# **CAPACITANCE CHARACTERISTICS**<sup>(1,2)</sup> (At TA = 0 to $+25^{\circ}$ C, VDD = VDDQ = $3.3 \pm 0.3$ V, f = 1 MHz)

Symbol	Parameter	Тур.	Max.	Unit
Cin	Input Capacitance: Address and Control	_	3.8	pF
Cclk	Input Capacitance: (CLK)	_	3.5	pF
CI/O	Data Input/Output Capacitance: I/O0-I/O15	_	6.5	pF

#### Notes:

- Stress greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a
  stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational
  sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect
  reliability.
- 2. All voltages are referenced to GND.
- 3.  $V_{IH}(max) = V_{DDQ} + 1.2V$  with a pulse width < 3ns.
- 4.  $V_{IL}(min) = GND 1.2V$  with a pulse width < 3ns.

# THERMAL RESISTANCE

Package	Substrate	Theta-ja (Airflow = 0m/s)	Theta-ja (Airflow = 1m/s)	Theta-ja (Airflow = 2m/s)	Theta-jc	Units
Alloy42 TSOP2(54)	4-layer	88.0	81	77.4	16.1	C/W
Copper TSOP2(54)	4-layer	51.7	49.0	47.7	11.9	C/W
BGA(54)	4-layer	50.5	44.6	41.7	11.3	C/W
BGA(60)	4-layer	48.3	42.3	41	7.5	C/W



# DC ELECTRICAL CHARACTERISTICS 1 (Recommended Operation Conditions unless otherwise noted.)

Symbol	Parameter	Test Condition	-5	-6	-7	Unit
IDD1 (1)	Operating Current	One bank active, CL = 3, BL = 1,	90	80	70	mA
		tclk = tclk (min), tRC = tRC (min)				
IDD2P	Precharge Standby Current (In Power-Down Mode)	$\frac{\text{CKE} \le \text{V}_{\text{IL}} \text{ (MAX), tck} = 15\text{ns}}{\overline{\text{CS}}} \ge \text{V}_{\text{DD}} - 0.2\text{V}$	2	2	2	mA
IDD2PS	Precharge Standby Current with clock stop (In Power-Down Mode)		2	2	2	mA
IDD2N (2)	Precharge Standby Current	$\overline{\text{CS}}  \geq \text{V}_{\text{DD}}  -  0.2 \text{V},  \text{CKE} \geq   \text{V}_{\text{IH}}                   $	20	20	20	mA
	(In Non Power-Down Mode)	tcκ = 15ns				
IDD2NS	Precharge Standby Current with clock stop	$\overline{\text{CS}} \geq \text{Vdd} - 0.2\text{V}, \text{CKE} \geq \text{Vih (Min)}$	10	10	10	mA
	(In Non Power-Down Mode)	All inputs stable				
IDD3P (2)	Active Standby Current	$CKE \le V_{IL} \text{ (MAX)}, \overline{CS} \ge V_{DD} - 0.2V$	6	6	6	mA
	(In Power-Down Mode)	tck = 15ns				
IDD3PS	Active Standby Current with clock stop (In Power-Down Mode)		6	6	6	mA
IDD3N (2)	Active Standby Current	$\overline{\text{CS}} \geq \text{V}_{\text{DD}} - 0.2 \text{V}, \text{CKE} \geq \text{V}_{\text{IH}} \text{ (MIN)}$	25	25	25	mA
	(In Non Power-Down Mode)	tcк = 15ns				
IDD3NS	Active Standby Current with clock stop	$\overline{\text{CS}} \geq \text{V}_{\text{DD}}$ - 0.2V, CKE $\geq \text{V}_{\text{IH}}$ (MIN) All inputs stable	20	20	20	mA
	(In Non Power-Down Mode)					
IDD4	Operating Current	All banks active, BL = 4, CL = 3,	110	100	90	mA
		tck = tck (min)				
IDD5	Auto-Refresh Current	trc = trc (min), tclk = tclk (min)	110	100	90	mA
IDD6	Self-Refresh Current	CKE ≤ 0.2V	2	2	2	mA

#### Notes:

- 1.  $\ensuremath{\mathsf{IDD}}$  (MAX) is specified at the output open condition.
- 2. Input signals are changed one time during 30ns.

# DC ELECTRICAL CHARACTERISTICS 2 (Recommended Operation Conditions unless otherwise noted.)

Symbol	Parameter	Test Condition	Min	Max	Unit
lıL	Input Leakage Current	$0V \le Vin \le V_{DD}$ , with pins other than	-5	5	μΑ
		the tested pin at 0V			
loL	Output Leakage Current	Output is disabled, $0V \le Vout \le V_{DD}$ ,	-5	5	μΑ
Vон	Output High Voltage Level	Iон = -2mA	2.4	_	V
VoL	Output Low Voltage Level	IoL = 2mA	_	0.4	V



# **AC ELECTRICAL CHARACTERISTICS** (1,2,3)

			-5		-6		-7		
Symbol	Parameter		Min.	Max.	Min.	Max.	Min.	Max.	Units
tскз	Clock Cycle Time	CAS Latency = 3	5	_	6	_	7	_	ns
tck2		CAS Latency = 2	7.5	_	7.5	_	7.5	_	ns
t <sub>AC3</sub>	Access Time From CLK(4,6)	$\overline{\text{CAS}}$ Latency = 3	_	4.8	_	5.4	_	5.4	ns
tAC2		CAS Latency = 2	_	5.4		5.4	_	5.4	ns
tсн	CLK HIGH Level Width		2		2		2.5		ns
tcL	CLK LOW Level Width		2	_	2	_	2.5	_	ns
tонз	Output Data Hold Time(6)	CAS Latency = 3	2.5	_	2.5	_	2.7	_	ns
toH2		CAS Latency = 2	2.5	_	2.5	_	2.7		ns
tız	Output LOW Impedance Time		0		0		0		ns
tHZ3	Output HIGH Impedance Time(5)	CAS Latency = 3	_	4.8	_	5.4	_	5.4	ns
tHZ2		CAS Latency = 2		5.4		5.4		5.4	ns
tos	Input Data Setup Time		1.5	_	1.5		1.5		ns
tdH	Input Data Hold Time		0.8		0.8		0.8		ns
tas	Address Setup Time		1.5	_	1.5	_	1.5	_	ns
tah	Address Hold Time		0.8	_	0.8	_	0.8		ns
tcks	CKE Setup Time		1.5		1.5		1.5		ns
tскн	CKE Hold Time		0.8		0.8	_	0.8	_	ns
tcka	CKE to CLK Recovery Delay Time	)	1CLK+3	_	1CLK+3	_	1CLK+3	_	ns
tcms	Command Setup Time ( $\overline{CS}$ , $\overline{RAS}$ ,	CAS, WE, DQM)	1.5	_	1.5	_	1.5	_	ns
tсмн	Command Hold Time (CS, RAS, C	CAS, WE, DQM)	0.8	_	0.8	_	0.8	_	ns
trc	Command Period (REF to REF / A	ACT to ACT)	55	_	60	_	63	_	ns
tras	Command Period (ACT to PRE)		40	100,000	42	100,000	42	100,000	ns
trp	Command Period (PRE to ACT)		15		15	_	15	_	ns
trcd	Active Command To Read / Write	Command Delay Time	15		15	_	15	_	ns
trrd	Command Period (ACT [0] to ACT	[1])	10		12	_	14	_	ns
tdpl or	Input Data To Precharge Command Delay time	CAS Latency = 3	2CLK	_	2CLK	_	2CLK	_	ns
		CAS Latency = 2	2CLK	_	2CLK	_	2CLK	_	ns
<b>t</b> DAL	Input Data To Active / Refresh Command Delay time	CAS Latency = 3	2CLK+trp	_	2CLK+trp	_	2CLK+trp	_	ns
	(During Auto-Precharge)	CAS Latency = 2	2CLK+trp	_	2CLK+trp	_	2CLK+trp	_	ns
tτ	Transition Time	-	0.3	1.2	0.3	1.2	0.3	1.2	ns
txsr	Exit Self-Refresh to Active Time		60	_	66	_	70	_	ns
tref	Refresh Cycle Time (4096)								
		Com., Ind., A1, A2	_	64	_	64	_	64	ms
	TA ≤ 8	35°C Ind., A1, A2	_	_	_	64	_	64	ms
Notes:		TA > 85°C A2	_			16		16	ms

#### Notes:

- 1. When power is first applied, memory operation should be started 200 µs after VDD and VDDQ reach their stipulated voltages. Also note that the power-on sequence must be executed before starting memory operation.
- 2. Measured with  $t_T = 1$  ns.
- 3. The reference level is 1.4 V when measuring input signal timing. Rise and fall times are measured between ViH (min.) and ViL (max.).
- 4. Access time is measured at 1.4V with the load shown in the figure below.
- 5. The time thz (max.) is defined as the time required for the output voltage to transition by ± 200 mV from VoH (min.) or VoL (max.) when the output is in the high impedance state.
- 6. If clock rising time is longer than 1ns,  $t\tau/2$  0.5ns should be added to the parameter.



# **OPERATING FREQUENCY / LATENCY RELATIONSHIPS**

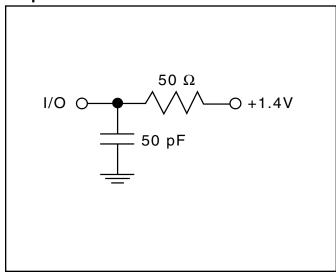
SYMBOL	PARAMETER		-5	-6	-7	UNITS
tcĸ	Clock Cycle Time	CL=3	5	6	7	ns
		CL=2	7.5	7.5	7.5	ns
Freq.	Operating Frequency	CL=3	200	166	143	MHz
		CL=2	133	133	133	MHz
tccd	READ/WRITE command to READ/WRITE of	command	1	1	1	cycle
tcked	CKE to clock disable or power-down entry n	node	1	1	1	cycle
tPED	CKE to clock enable or power-down exit set	up mode	1	1	1	cycle
toqo	DQM to input data delay	0	0	0	cycle	
tDQM	DQM to data mask during WRITEs	0	0	0	cycle	
toqz	DQM to data high-impedance during READ	S	2	2	2	cycle
towo	WRITE command to input data delay		0	0	0	cycle
tDAL	Data-in to ACTIVE command	CL=3	5	5	5	cycle
		CL=2	4	4	4	cycle
tDPL	Data-in to PRECHARGE command		2	2	2	cycle
tBDL	Last data-in to burst STOP command		1	1	1	cycle
tcdl	Last data-in to new READ/WRITE command	d	1	1	1	cycle
trdl	Last data-in to PRECHARGE command		2	2	2	cycle
tmrd	LOAD MODE REGISTER command		2	2	2	cycle
	to ACTIVE or REFRESH command					-
tпон	Data-out to high-impedance from	CL=3	3	3	3	cycle
	PRECHARGE command	CL=2	2	2	2	cycle

# ACTEST CONDITIONS (Input/Output Reference Level: 1.4V)

# **Input Load**

# 

# **Output Load**





#### **FUNCTIONAL DESCRIPTION**

The 64Mb SDRAMs (1 Meg x 16 x 4 banks) are quad-bank DRAMs which operate at 3.3V and include a synchronous interface (all signals are registered on the positive edge of the clock signal, CLK). Each of the 16,777,216-bit banks is organized as 4,096 rows by 256 columns by 16 bits.

Read and write accesses to the SDRAM are burst oriented; accesses start at a selected location and continue for a programmed number of locations in a programmed sequence. Accesses begin with the registration of an ACTIVE command which is then followed by a READ or WRITE command. The address bits registered coincident with the ACTIVE command are used to select the bank and row to be accessed (BA0 and BA1 select the bank, A0-A11 select the row). The address bits (A0-A7) registered coincident with the READ or WRITE command are used to select the starting column location for the burst access.

Prior to normal operation, the SDRAM must be initialized. The following sections provide detailed information covering device initialization, register definition, command descriptions and device operation.

#### Initialization

SDRAMs must be powered up and initialized in a predefined manner.

The 64Mb SDRAM is initialized after the power is applied to VDD and VDDQ (simultaneously), and the clock is stable with DQM High and CKE High.

A 100µs delay is required prior to issuing any command other than a COMMAND INHIBIT or a NOP. The COMMAND INHIBIT or NOP may be applied during the 100µs period and continue should at least through the end of the period.

With at least one COMMAND INHIBIT or NOP command having been applied, a PRECHARGE command should be applied once the 100µs delay has been satisfied. All banks must be precharged. This will leave all banks in an idle state, after which at least two AUTO REFRESH cycles must be performed. After the AUTO REFRESH cycles are complete, the SDRAM is then ready for mode register programming.

The mode register should be loaded prior to applying any operational command because it will power up in an unknown state. After the Load Mode Register command, at least one NOP command must be asserted prior to any command.



#### REGISTER DEFINITION

## **Mode Register**

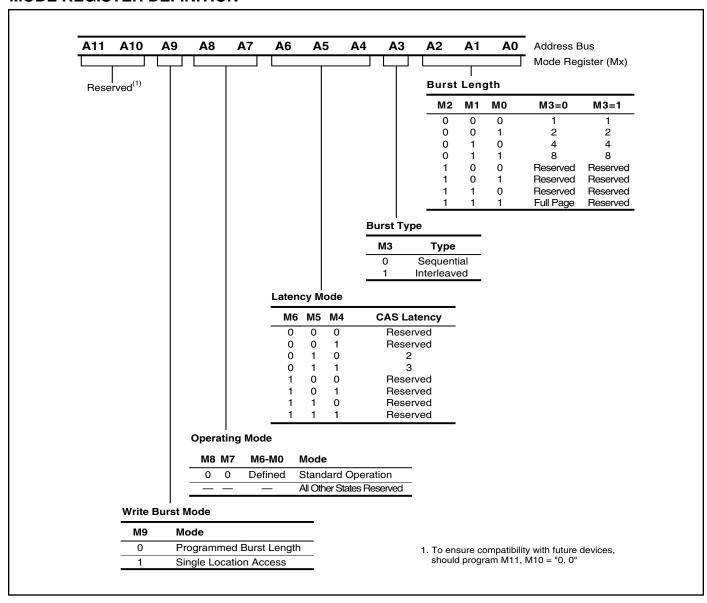
The mode register is used to define the specific mode of operation of the SDRAM. This definition includes the selection of a burst length, a burst type, a CAS latency, an operating mode and a write burst mode, as shown in MODE REGISTER DEFINITION.

The mode register is programmed via the LOAD MODE REGISTER command and will retain the stored information until it is programmed again or the device loses power.

Mode register bits M0-M2 specify the burst length, M3 specifies the type of burst (sequential or interleaved), M4-M6 specify the CAS latency, M7 and M8 specify the operating mode, M9 specifies the WRITE burst mode, and M10 and M11 are reserved for future use.

The mode register must be loaded when all banks are idle, and the controller must wait the specified time before initiating the subsequent operation. Violating either of these requirements will result in unspecified operation.

#### MODE REGISTER DEFINITION





# **Burst Length**

Read and write accesses to the SDRAM are burst oriented, with the burst length being programmable, as shown in MODE REGISTER DEFINITION. The burst length determines the maximum number of column locations that can be accessed for a given READ or WRITE command. Burst lengths of 1, 2, 4 or 8 locations are available for both the sequential and the interleaved burst types, and a full-page burst is available for the sequential type. The full-page burst is used in conjunction with the BURST TERMINATE command to generate arbitrary burst lengths.

Reserved states should not be used, as unknown operation or incompatibility with future versions may result.

When a READ or WRITE command is issued, a block of columns equal to the burst length is effectively selected. All accesses for that burst take place within this block, mean-

ing that the burst will wrap within the block if a boundary is reached. The block is uniquely selected by A1-A7 (x16) when the burst length is set to two; by A2-A7 (x16) when the burst length is set to four; and by A3-A7 (x16) when the burst length is set to eight. The remaining (least significant) address bit(s) is (are) used to select the starting location within the block. Full-page bursts wrap within the page if the boundary is reached.

# **Burst Type**

Accesses within a given burst may be programmed to be either sequential or interleaved; this is referred to as the burst type and is selected via bit M3.

The ordering of accesses within a burst is determined by the burst length, the burst type and the starting column address, as shown in BURST DEFINITION table.

#### **BURST DEFINITION**

Burst	Burst Starting Column		umn	Order of Acce	esses Within a Burst
Length	yth Address		<b>;</b>	Type = Sequential	Type = Interleaved
			A0		
2			0	0-1	0-1
			1	1-0	1-0
		<b>A</b> 1	A0		
		0	0	0-1-2-3	0-1-2-3
4		0	1	1-2-3-0	1-0-3-2
		1	0	2-3-0-1	2-3-0-1
		1	1	3-0-1-2	3-2-1-0
	A2	A1	A0		
	0	0	0	0-1-2-3-4-5-6-7	0-1-2-3-4-5-6-7
	0	0	1	1-2-3-4-5-6-7-0	1-0-3-2-5-4-7-6
	0	1	0	2-3-4-5-6-7-0-1	2-3-0-1-6-7-4-5
8	0	1	1	3-4-5-6-7-0-1-2	3-2-1-0-7-6-5-4
	1	0	0	4-5-6-7-0-1-2-3	4-5-6-7-0-1-2-3
	1	0	1	5-6-7-0-1-2-3-4	5-4-7-6-1-0-3-2
	1	1	0	6-7-0-1-2-3-4-5	6-7-4-5-2-3-0-1
	1	1	1	7-0-1-2-3-4-5-6	7-6-5-4-3-2-1-0
Full Page	n = A0-A7			Cn, Cn + 1, Cn + 2 Cn + 3, Cn + 4	Not Supported
(y)	(location 0-	·y)		Cn - 1, Cn	



### **CAS Latency**

The CAS latency is the delay, in clock cycles, between the registration of a READ command and the availability of the first piece of output data. The latency can be set to two or three clocks.

If a READ command is registered at clock edge n, and the latency is m clocks, the data will be available by clock edge n + m. The DQs will start driving as a result of the clock edge one cycle earlier (n + m - 1), and provided that the relevant access times are met, the data will be valid by clock edge n + m. For example, assuming that the clock cycle time is such that all relevant access times are met, if a READ command is registered at T0 and the latency is programmed to two clocks, the DQs will start driving after T1 and the data will be valid by T2, as shown in CAS Latency diagrams. The **Allowable Operating Frequency** table indicates the operating frequencies at which each CAS latency setting can be used.

Reserved states should not be used as unknown operation or incompatibility with future versions may result.

# **Operating Mode**

The normal operating mode is selected by setting M7 and M8 to zero; the other combinations of values for M7 and M8 are reserved for future use and/or test modes. The programmed burst length applies to both READ and WRITE bursts.

Test modes and reserved states should not be used because unknown operation or incompatibility with future versions may result.

#### **Write Burst Mode**

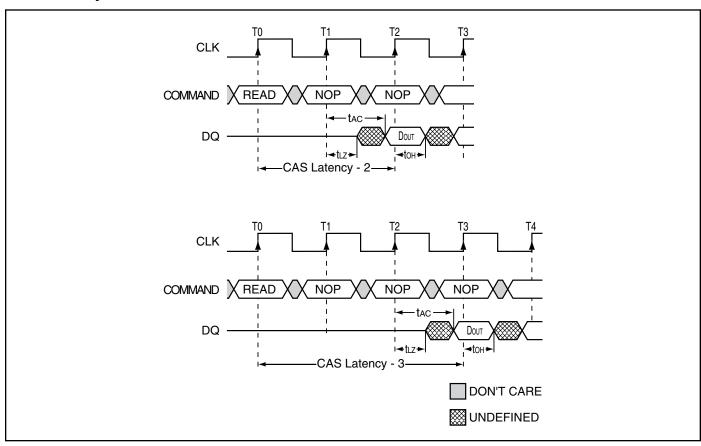
When M9 = 0, the burst length programmed via M0-M2 applies to both READ and WRITE bursts; when M9 = 1, the programmed burst length applies to READ bursts, but write accesses are single-location (nonburst) accesses.

# CAS Latency

# Allowable Operating Frequency (MHz)

Speed	CAS Latency = 2	CAS Latency = 3
-5	133	200
-6	133	166
-7	133	143

# **CAS Latency**





#### **OPERATION**

#### BANK/ROW ACTIVATION

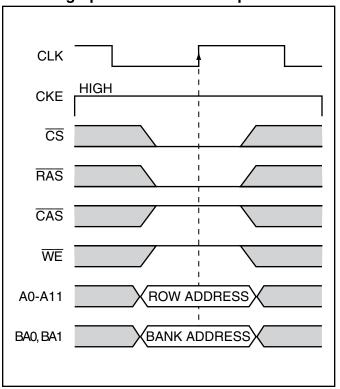
Before any READ or WRITE commands can be issued to a bank within the SDRAM, a row in that bank must be "opened." This is accomplished via the ACTIVE command, which selects both the bank and the row to be activated (see Activating Specific Row Within Specific Bank).

After opening a row (issuing an ACTIVE command), a READ or WRITE command may be issued to that row, subject to the trace specification. Minimum trace should be divided by the clock period and rounded up to the next whole number to determine the earliest clock edge after the ACTIVE command on which a READ or WRITE command can be entered. For example, a trace specification of 20ns with a 125 MHz clock (8ns period) results in 2.5 clocks, rounded to 3. This is reflected in the following example, which covers any case where 2 < [trace (MIN)/tck]  $\leq$  3. (The same procedure is used to convert other specification limits from time units to clock cycles).

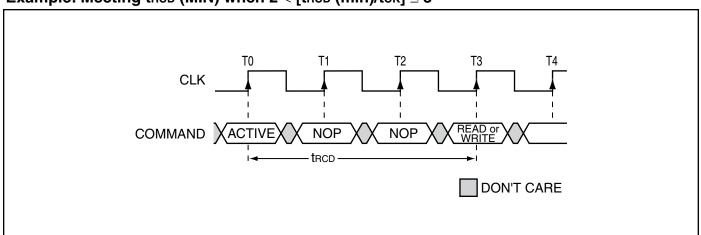
A subsequent ACTIVE command to a different row in the same bank can only be issued after the previous active row has been "closed" (precharged). The minimum time interval between successive ACTIVE commands to the same bank is defined by trc.

A subsequent ACTIVE command to another bank can be issued while the first bank is being accessed, which results in a reduction of total row-access overhead. The minimum time interval between successive ACTIVE commands to different banks is defined by trad.

# **Activating Specific Row Within Specific Bank**



# Example: Meeting trcd (MIN) when $2 < [trcd (min)/tck] \le 3$





#### **READS**

READ bursts are initiated with a READ command, as shown in the READ COMMAND diagram.

The starting column and bank addresses are provided with the READ command, and auto precharge is either enabled or disabled for that burst access. If auto precharge is enabled, the row being accessed is precharged at the completion of the burst. For the generic READ commands used in the following illustrations, auto precharge is disabled.

During READ bursts, the valid data-out element from the starting column address will be available following the CAS latency after the READ command. Each subsequent data-out element will be valid by the next positive clock edge. The CAS Latency diagram shows general timing for each possible CAS latency setting.

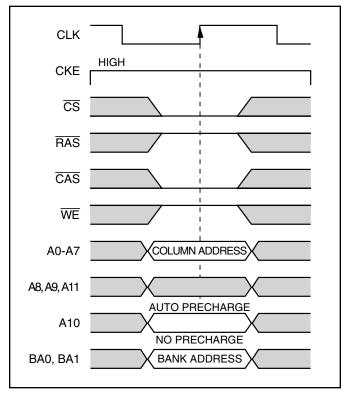
Upon completion of a burst, assuming no other commands have been initiated, the DQs will go High-Z. A full-page burst will continue until terminated. (At the end of the page, it will wrap to column 0 and continue.)

Data from any READ burst may be truncated with a subsequent READ command, and data from a fixed-length READ burst may be immediately followed by data from a READ command. In either case, a continuous flow of data can be maintained. The first data element from the new burst follows either the last element of a completed burst or the last desired data element of a longer burst which is being truncated.

The new READ command should be issued x cycles before the clock edge at which the last desired data element is valid, where x equals the CAS latency minus one. This is shown in Consecutive READ Bursts for CAS latencies of two and three; data element n+3 is either the last of a burst of four or the last desired of a longer burst. The 64Mb SDRAM uses a pipelined architecture and therefore does not require the 2n rule associated with a prefetch architecture. A READ command can be initiated on any clock cycle following a previous READ command. Full-speed random read accesses can be performed to the same bank, as shown in Random READ Accesses, or each subsequent READ may be performed to a different bank.

Data from any READ burst may be truncated with a subsequent WRITE command, and data from a fixed-length READ burst may be immediately followed by data from a WRITE command (subject to bus turnaround limitations). The WRITE burst may be initiated on the clock edge immediately following the last (or last desired) data element from the READ burst, provided that I/O contention can be avoided. In a given system design, there may be a possibility that the device driving the input data will go Low-Z before the SDRAM DQs go High-Z. In this case, at least a single-cycle delay should occur between the last read data and the WRITE command.

#### **READ COMMAND**



The DQM input is used to avoid I/O contention, as shown in Figures RW1 and RW2. The DQM signal must be asserted (HIGH) at least three clocks prior to the WRITE command (DQM latency is two clocks for output buffers) to suppress data-out from the READ. Once the WRITE command is registered, the DQs will go High-Z (or remain High-Z), regardless of the state of the DQM signal, provided the DQM was active on the clock just prior to the WRITE command that truncated the READ command. If not, the second WRITE will be an invalid WRITE. For example, if DQM was LOW during T4 in Figure RW2, then the WRITEs at T5 and T7 would be valid, while the WRITE at T6 would be invalid.

The DQM signal must be de-asserted prior to the WRITE command (DQM latency is zero clocks for input buffers) to ensure that the written data is not masked.

A fixed-length READ burst may be followed by, or truncated with, a PRECHARGE command to the same bank (provided that auto precharge was not activated), and a full-page burst may be truncated with a PRECHARGE command to the same bank. The PRECHARGE command should be issued  $\boldsymbol{x}$  cycles before the clock edge at which the last desired data element is valid, where  $\boldsymbol{x}$  equals the CAS latency minus one. This is shown in the READ to PRECHARGE

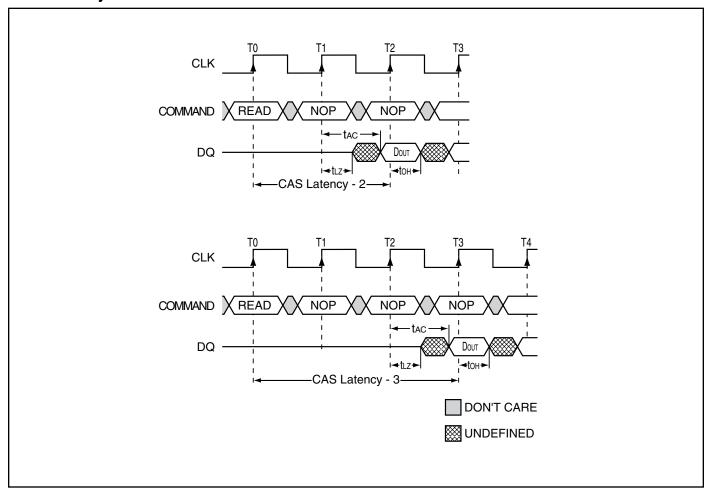


diagram for each possible CAS latency; data element n+3 is either the last of a burst of four or the last desired of a longer burst. Following the PRECHARGE command, a subsequent command to the same bank cannot be issued until the is met. Note that part of the row precharge time is hidden during the access of the last data element(s).

In the case of a fixed-length burst being executed to completion, a PRECHARGE command issued at the optimum time (as described above) provides the same operation that would result from the same fixed-length burst with auto precharge. The disadvantage of the PRECHARGE command is that it requires that the command and address buses be available at the appropriate time to issue the command; the advantage of the PRECHARGE command is that it can be used to truncate fixed-length or full-page bursts.

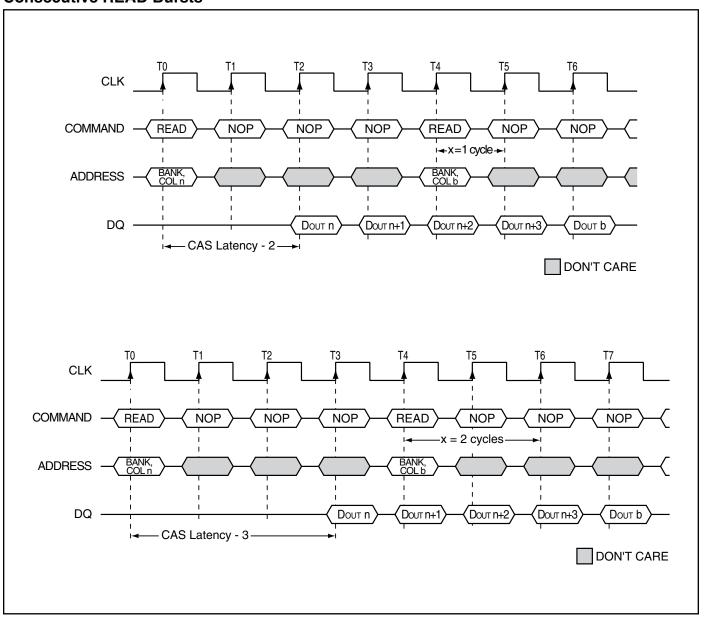
Full-page READ bursts can be truncated with the BURST TERMINATE command, and fixed-length READ bursts may be truncated with a BURST TERMINATE command, provided that auto precharge was not activated. The BURST TERMINATE command should be issued x cycles before the clock edge at which the last desired data element is valid, where x equals the CAS latency minus one. This is shown in the READ Burst Termination diagram for each possible CAS latency; data element n+3 is the last desired data element of a longer burst.

# **CAS Latency**



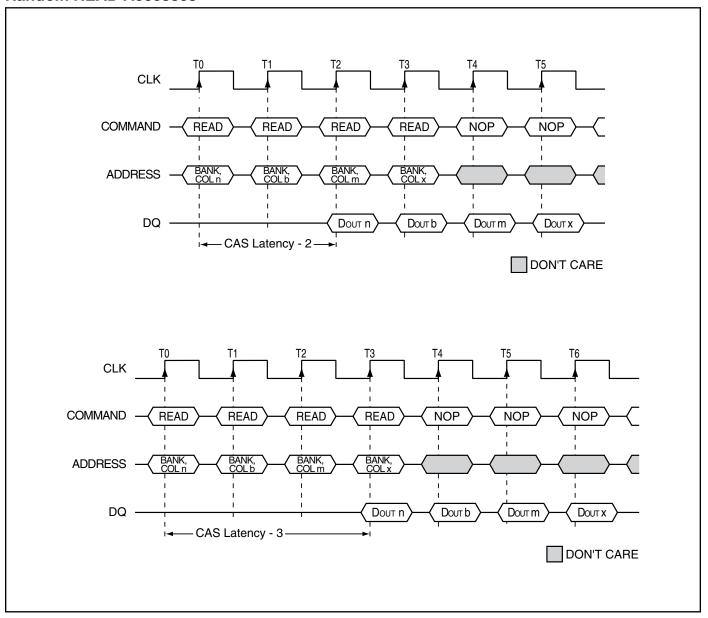


# **Consecutive READ Bursts**



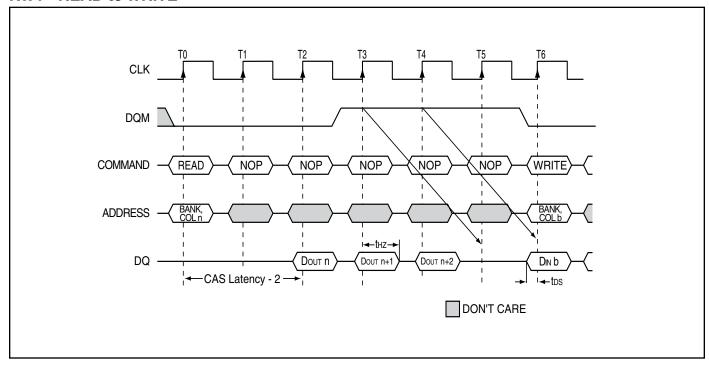


# **Random READ Accesses**

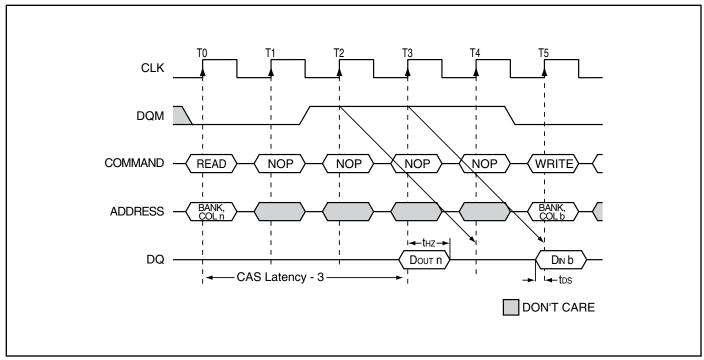




# **RW1 - READ to WRITE**

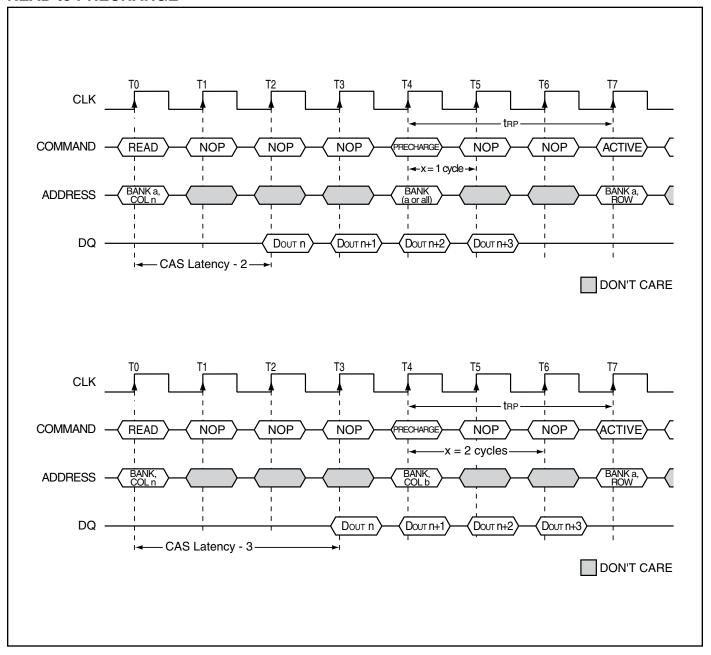


# **RW2 - READ to WRITE**



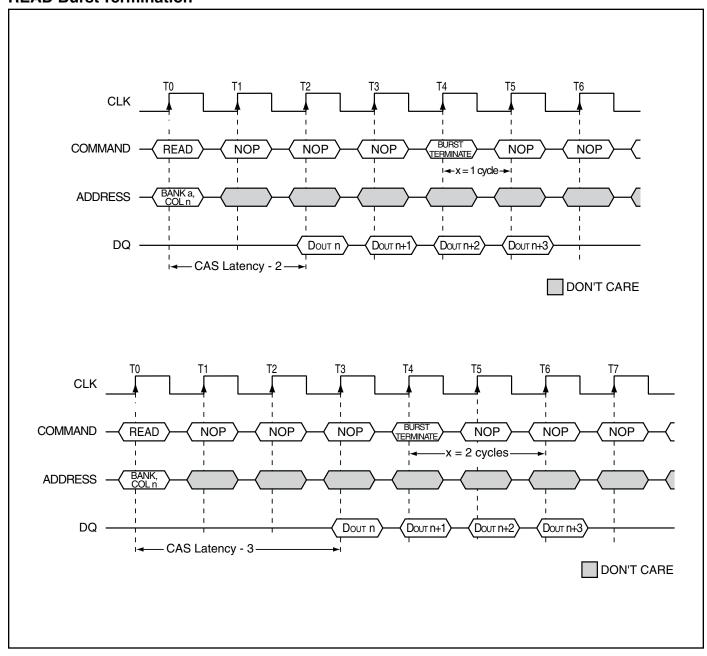


# **READ to PRECHARGE**





# **READ Burst Termination**

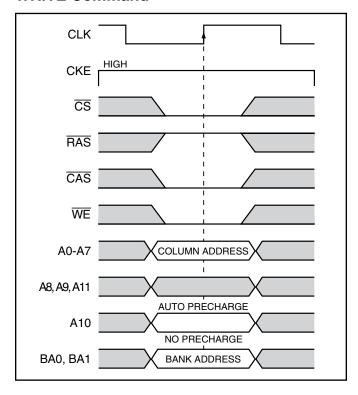




#### **WRITEs**

WRITE bursts are initiated with a WRITE command, as shown in WRITE Command diagram.

#### WRITE Command



The starting column and bank addresses are provided with the WRITE command, and auto precharge is either enabled or disabled for that access. If auto precharge is enabled, the row being accessed is precharged at the completion of the burst. For the generic WRITE commands used in the following illustrations, auto precharge is disabled.

During WRITE bursts, the first valid data-in element will be registered coincident with the WRITE command. Subsequent data elements will be registered on each successive positive clock edge. Upon completion of a fixed-length burst, assuming no other commands have been initiated, the DQs will remain High-Z and any additional input data will be ignored (see WRITE Burst). A full-page burst will continue until terminated. (At the end of the page, it will wrap to column 0 and continue.)

Data for any WRITE burst may be truncated with a subsequent WRITE command, and data for a fixed-length WRITE burst may be immediately followed by data for a WRITE command. The new WRITE command can be issued on any clock following the previous WRITE command, and the data provided coincident with the new command applies to the new command.

An example is shown in WRITE to WRITE diagram. Data n+1 is either the last of a burst of two or the last desired of a longer burst. The 64Mb SDRAM uses a pipelined architecture and therefore does not require the 2n rule associated with a prefetch architecture. A WRITE command can be initiated on any clock cycle following a previous WRITE command. Full-speed random write accesses within a page can be performed to the same bank, as shown in Random WRITE Cycles, or each subsequent WRITE may be performed to a different bank.

Data for any WRITE burst may be truncated with a subsequent READ command, and data for a fixed-length WRITE burst may be immediately followed by a subsequent READ command. Once the READ command is registered, the data inputs will be ignored, and WRITEs will not be executed. An example is shown in WRITE to READ. Data n + 1 is either the last of a burst of two or the last desired of a longer burst.

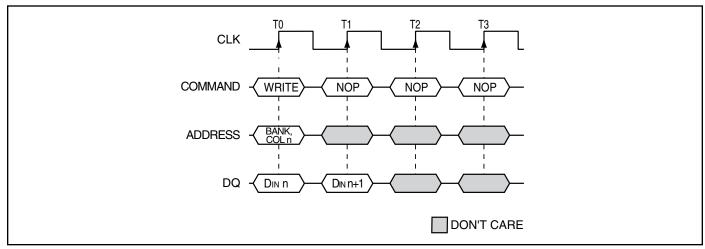
Data for a fixed-length WRITE burst may be followed by, or truncated with, a PRECHARGE command to the same bank (provided that auto precharge was not activated), and a full-page WRITE burst may be truncated with a PRECHARGE command to the same bank. The PRECHARGE command should be issued twn after the clock edge at which the last desired input data element is registered. The auto precharge mode requires a twn of at least one clock plus time, regardless of frequency. In addition, when truncating a WRITE burst, the DQM signal must be used to mask input data for the clock edge prior to, and the clock edge coincident with, the PRECHARGE command. An example is shown in the WRITE to PRE-CHARGE diagram. Data n+1 is either the last of a burst of two or the last desired of a longer burst. Following the PRECHARGE command, a subsequent command to the same bank cannot be issued until tRP is met.

In the case of a fixed-length burst being executed to completion, a PRECHARGE command issued at the optimum time (as described above) provides the same operation that would result from the same fixed-length burst with auto precharge. The disadvantage of the PRECHARGE command is that it requires that the command and address buses be available at the appropriate time to issue the command; the advantage of the PRECHARGE command is that it can be used to truncate fixed-length or full-page bursts.

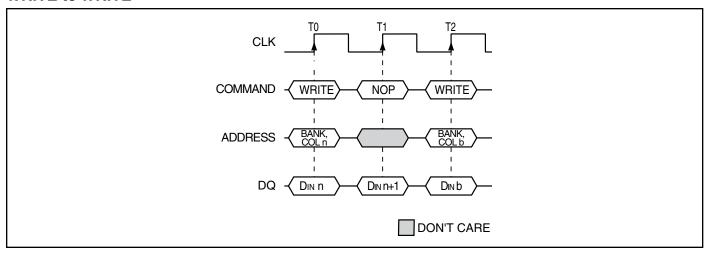
Fixed-length or full-page WRITE bursts can be truncated with the BURST TERMINATE command. When truncating a WRITE burst, the input data applied coincident with the BURST TERMINATE command will be ignored. The last data written (provided that DQM is LOW at that time) will be the input data applied one clock previous to the BURST TERMINATE command. This is shown in WRITE Burst Termination, where data n is the last desired data element of a longer burst.



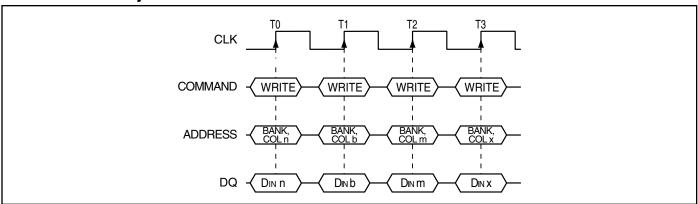
## **WRITE Burst**



# **WRITE to WRITE**

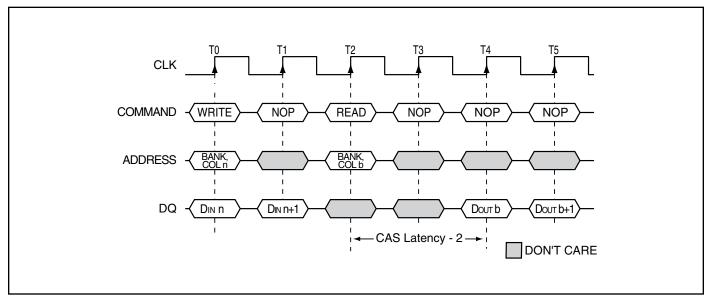


# **Random WRITE Cycles**

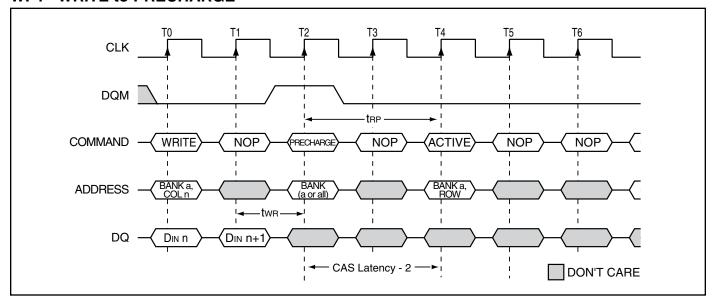




# **WRITE to READ**

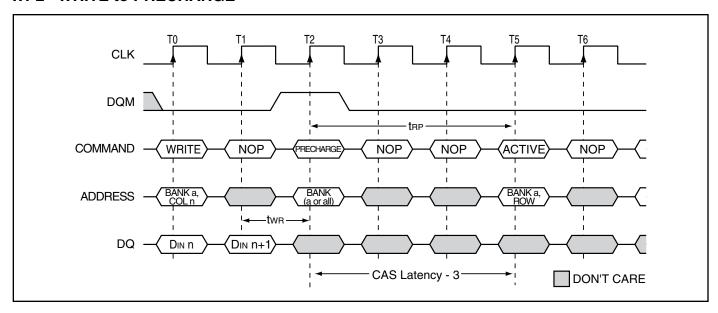


## **WP1 - WRITE to PRECHARGE**

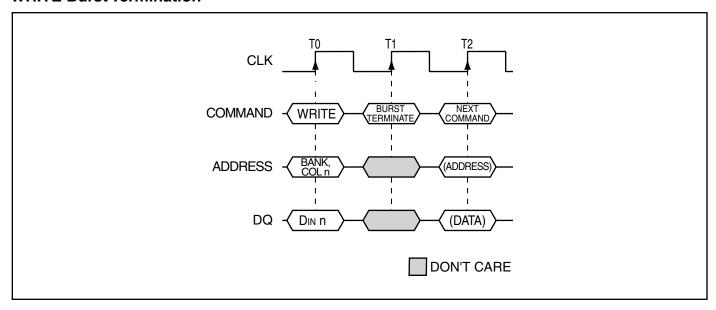




## **WP2 - WRITE to PRECHARGE**



## **WRITE Burst Termination**





#### **PRECHARGE**

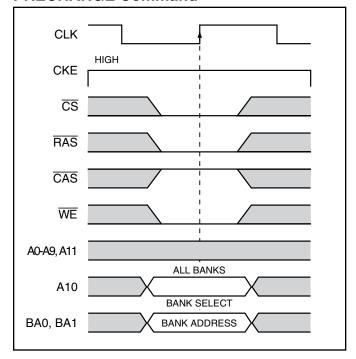
The PRECHARGE command (see figure) is used to deactivate the open row in a particular bank or the open row in all banks. The bank(s) will be available for a subsequent row access some specified time (trp) after the PRECHARGE command is issued. Input A10 determines whether one or all banks are to be precharged, and in the case where only one bank is to be precharged, inputs BA0, BA1 select the bank. When all banks are to be precharged, inputs BA0, BA1 are treated as "Don't Care." Once a bank has been precharged, it is in the idle state and must be activated prior to any READ or WRITE commands being issued to that bank.

#### **POWER-DOWN**

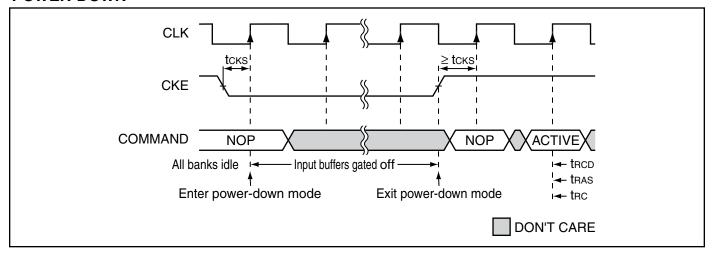
Power-down occurs if CKE is registered LOW coincident with a NOP or COMMAND INHIBIT when no accesses are in progress. If power-down occurs when all banks are idle, this mode is referred to as precharge power-down; if power-down occurs when there is a row active in either bank, this mode is referred to as active power-down. Entering power-down deactivates the input and output buffers, excluding CKE, for maximum power savings while in standby. The device may not remain in the power-down state longer than the refresh period (64ms) since no refresh operations are performed in this mode.

The power-down state is exited by registering a NOP or COMMAND INHIBIT and CKE HIGH at the desired clock edge (meeting tcks). See figure below.

#### PRECHARGE Command



#### **POWER-DOWN**





#### **CLOCK SUSPEND**

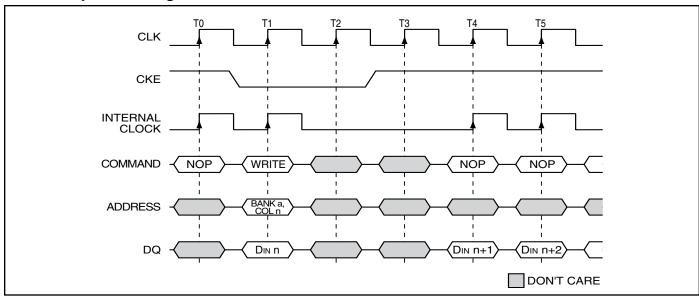
Clock suspend mode occurs when a column access/burst is in progress and CKE is registered LOW. In the clock suspend mode, the internal clock is deactivated, "freezing" the synchronous logic.

For each positive clock edge on which CKE is sampled LOW, the next internal positive clock edge is suspended. Any command or data present on the input pins at the time

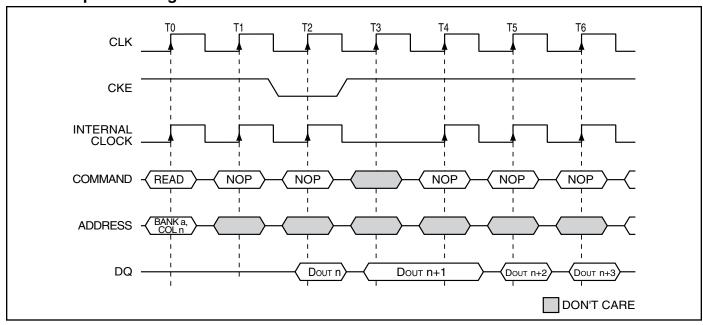
of a suspended internal clock edge is ignored; any data present on the DQ pins remains driven; and burst counters are not incremented, as long as the clock is suspended. (See following examples.)

Clock suspend mode is exited by registering CKE HIGH; the internal clock and related operation will resume on the subsequent positive clock edge.

# **Clock Suspend During WRITE Burst**



## **Clock Suspend During READ Burst**





#### **BURST READ/SINGLE WRITE**

The burst read/single write mode is entered by programming the write burst mode bit (M9) in the mode register to a logic 1. In this mode, all WRITE commands result in the access of a single column location (burst of one), regardless of the programmed burst length. READ commands access columns according to the programmed burst length and sequence, just as in the normal mode of operation (M9 = 0).

#### **CONCURRENT AUTO PRECHARGE**

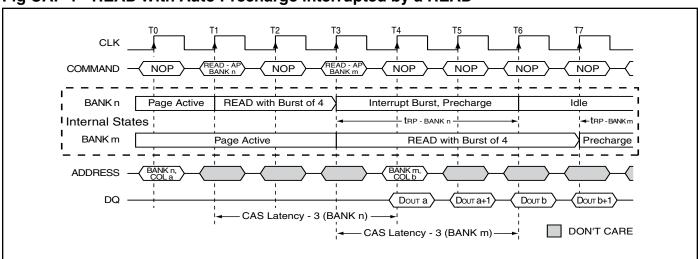
An access command (READ or WRITE) to another bank while an access command with auto precharge enabled is executing is not allowed by SDRAMs, unless the SDRAM supports CONCURRENT AUTO PRECHARGE. *ISSI* 

SDRAMs support CONCURRENT AUTO PRECHARGE. Four cases where CONCURRENT AUTO PRECHARGE occurs are defined below.

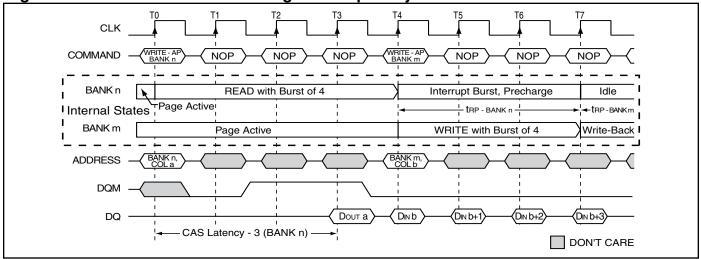
# **READ** with Auto Precharge

- Interrupted by a READ (with or without auto precharge):
   A READ to bank m will interrupt a READ on bank n,
   CAS latency later. The PRECHARGE to bank n will begin when the READ to bank m is registered.
- 2. Interrupted by a WRITE (with or without auto precharge): A WRITE to bank m will interrupt a READ on bank n when registered. DQM should be used two clocks prior to the WRITE command to prevent bus contention. The PRECHARGE to bank n will begin when the WRITE to bank m is registered.

Fig CAP 1 - READ With Auto Precharge interrupted by a READ









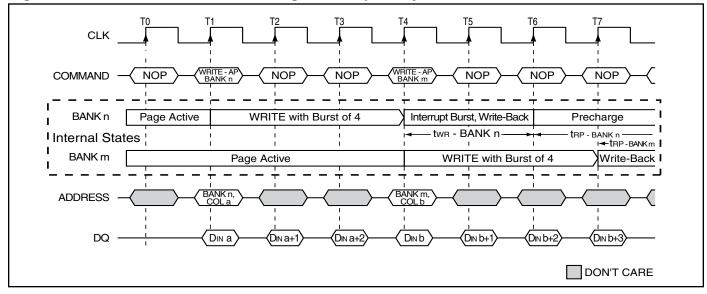
## WRITE with Auto Precharge

- 3. Interrupted by a READ (with or without auto precharge): A READ to bank m will interrupt a WRITE on bank n when registered, with the data-out appearing CAS latency later. The PRECHARGE to bank n will begin after twn is met, where twn begins when the READ to bank m is registered. The last valid WRITE to bank n will be data-in registered one clock prior to the READ to bank m.
- 4. Interrupted by a WRITE (with or without auto precharge): AWRITE to bank m will interrupt a WRITE on bank n when registered. The PRECHARGE to bank n will begin after twn is met, where twn begins when the WRITE to bank m is registered. The last valid data WRITE to bank n will be data registered one clock prior to a WRITE to bank m.

CLK NOP COMMAND NOP NOP NOP Interrupt Burst, Write-Back BANK n Page Active WRITE with Burst of 4 Precharge twn - BANK n · **t**RP - BANK n Internal States . I<del>≪</del>trp-bankm I BANK m Page Active READ with Burst of 4 Precharge I **ADDRESS** Dın a Dout b DQ (Dın a+1 Dout b+1 CAS Latency - 3 (BANK m) DON'T CARE

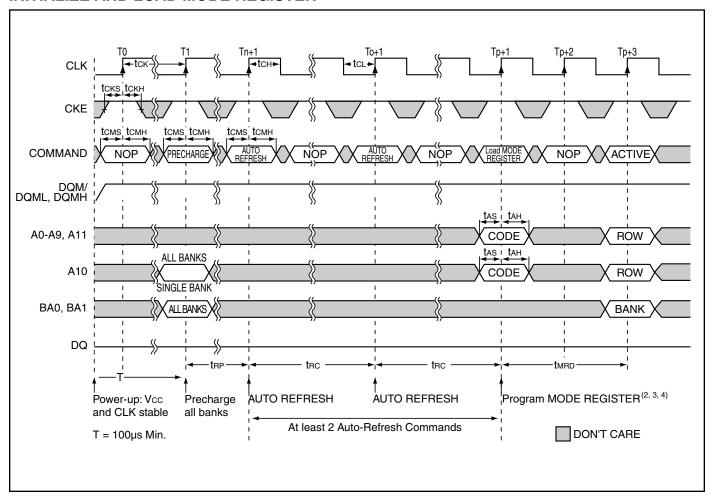
Fig CAP 3 - WRITE With Auto Precharge interrupted by a READ







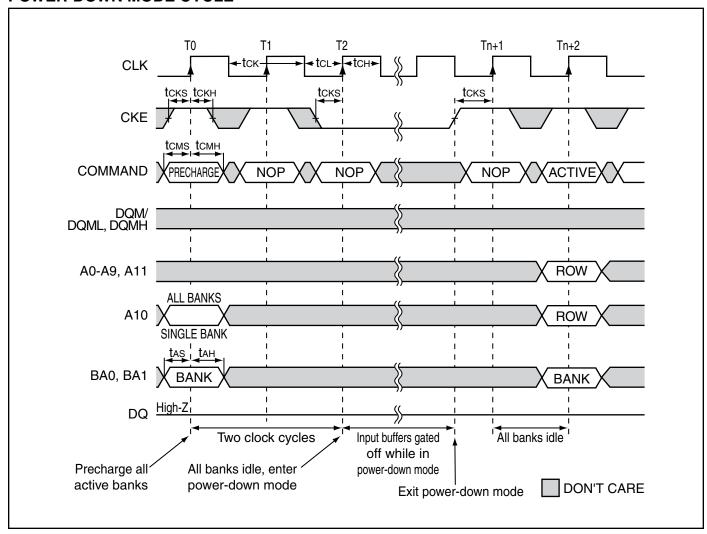
## INITIALIZE AND LOAD MODE REGISTER(1)



- If CS is High at clock High time, all commands applied are NOP.
   The Mode register may be loaded prior to the Auto-Refresh cycles if desired.
- 3. JEDEC and PC100 specify three clocks.
- 4. Outputs are guaranteed High-Z after the command is issued.



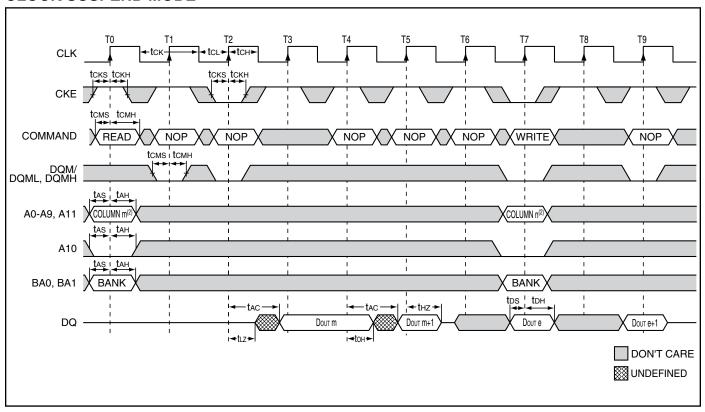
# **POWER-DOWN MODE CYCLE**



CAS latency = 2, 3



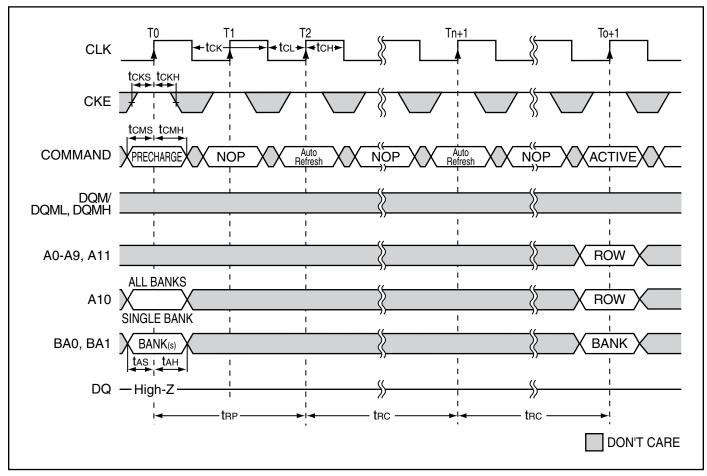
# **CLOCK SUSPEND MODE**



- 1.  $\overline{CAS}$  latency = 3, burst length = 2
- 2. A8, A9, and A11 = "Don't Care"



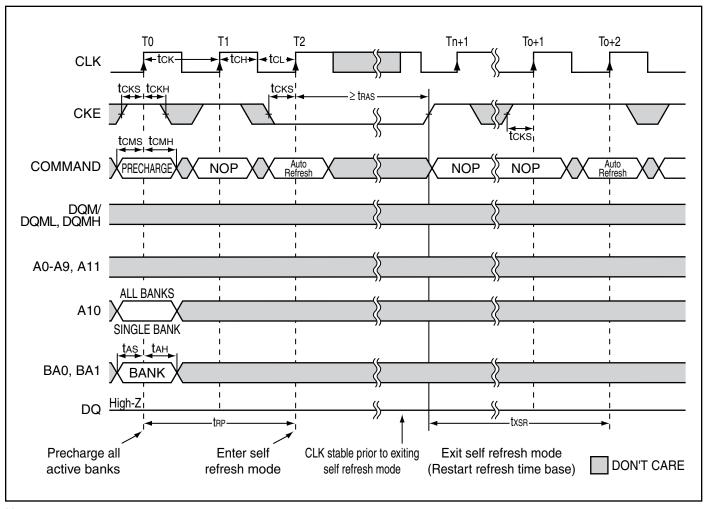
# **AUTO-REFRESH CYCLE**



 $\overline{CAS}$  latency = 2, 3



#### **SELF-REFRESH CYCLE**

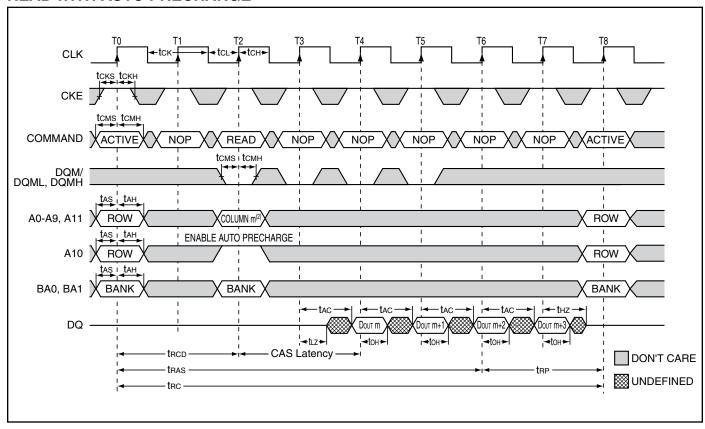


Note:

1. Self-Refresh Mode is not supported for A2 grade with T<sub>A</sub> > 85°C.



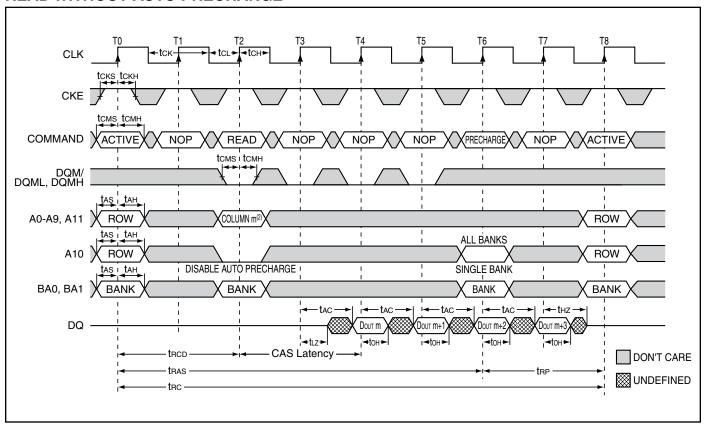
# **READ WITH AUTO PRECHARGE**



- 1.  $\overline{CAS}$  latency = 2, burst length = 4
- 2. A8, A9, and A11 = "Don't Care"



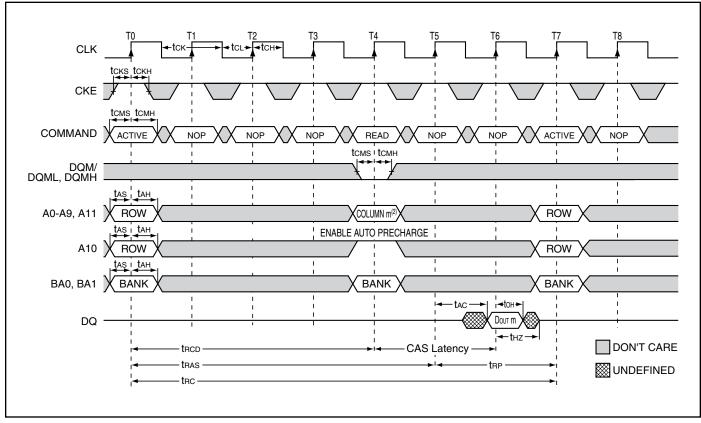
# **READ WITHOUT AUTO PRECHARGE**



- 1.  $\overline{CAS}$  latency = 2, burst length = 4
- 2. A8, A9, and A11 = "Don't Care"



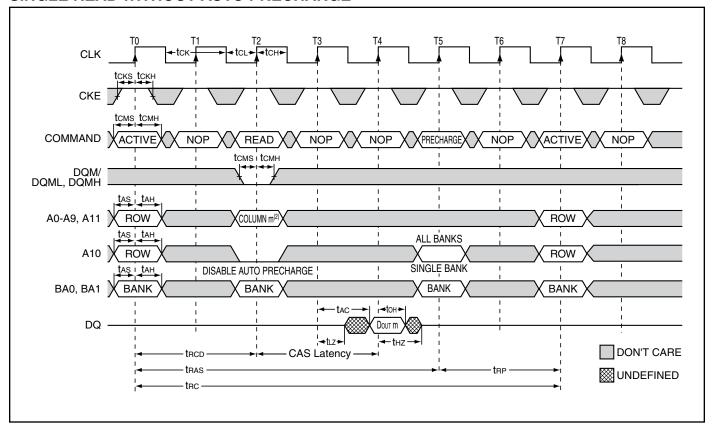
# SINGLE READ WITH AUTO PRECHARGE



- 1. CAS latency = 2, burst length = 1
- 2. A8, A9, and A11 = "Don't Care"



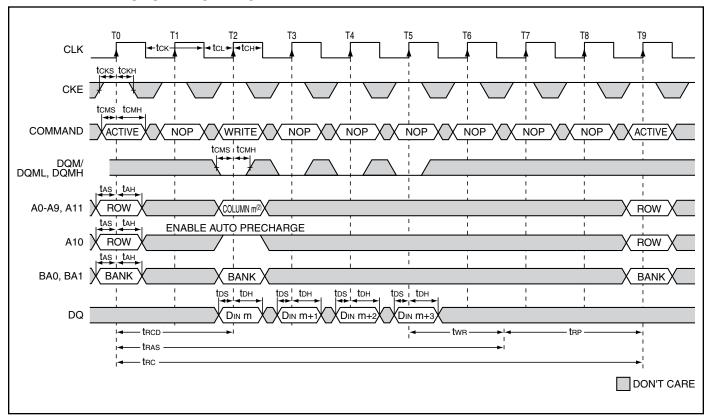
# SINGLE READ WITHOUT AUTO PRECHARGE



- 1.  $\overline{CAS}$  latency = 2, burst length = 1
- 2. A8, A9, and A11 = "Don't Care"



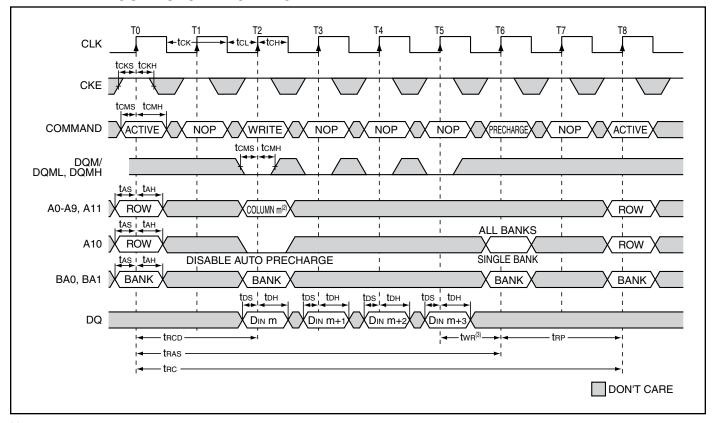
# **WRITE - WITH AUTO PRECHARGE**



- 1. burst length = 4
- 2. A8, A9, and A11 = "Don't Care"



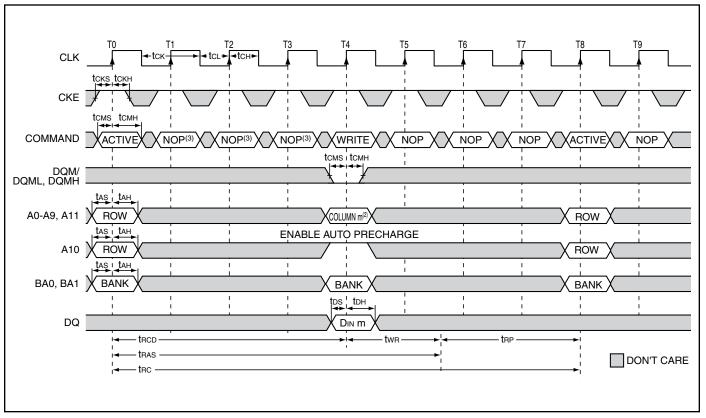
# **WRITE - WITHOUT AUTO PRECHARGE**



- 1. burst length = 4
- 2. A8, A9, and A11 = "Don't Care"
- 3. tras must not be violated



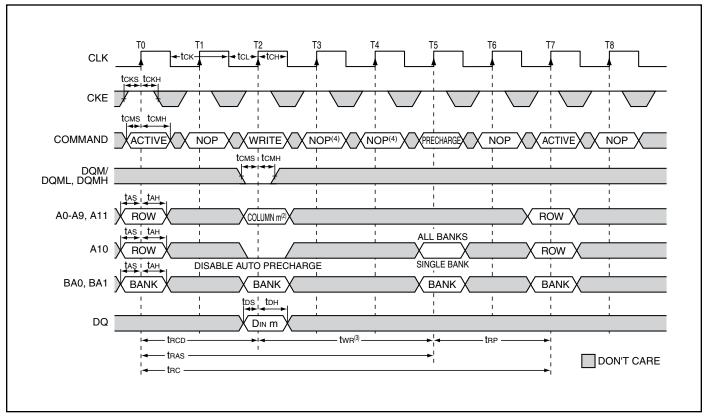
# SINGLE WRITE - WITH AUTO PRECHARGE



- 1. burst length = 1
- 2. A8, A9, and A11 = "Don't Care"



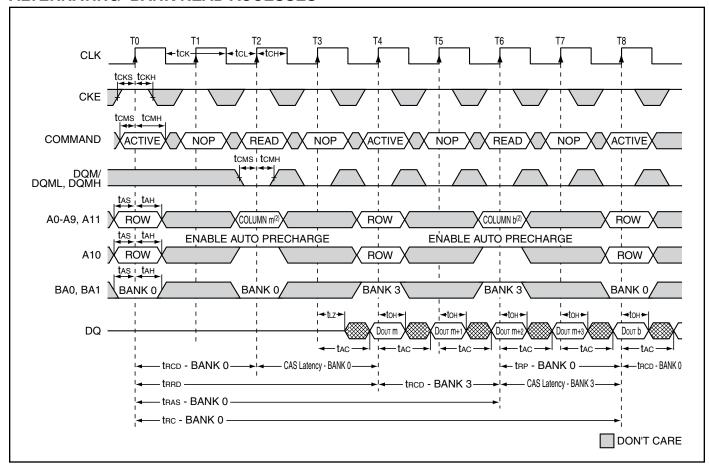
# SINGLE WRITE - WITHOUT AUTO PRECHARGE



- 1. burst length = 1
- 2. A8, A9, and A11 = "Don't Care"
- 3. tras must not be violated



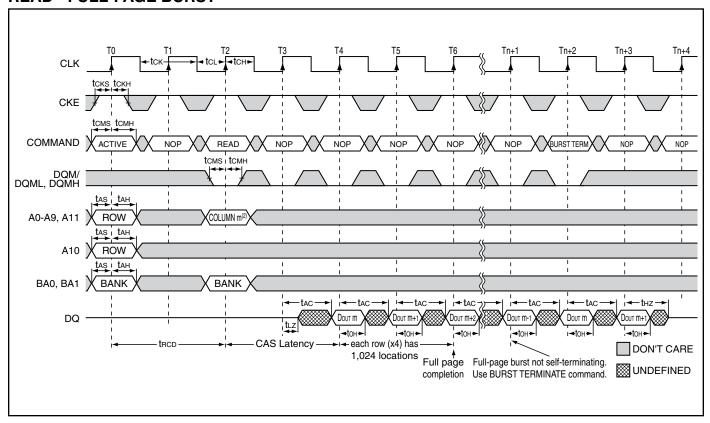
#### **ALTERNATING BANK READ ACCESSES**



- 1.  $\overline{CAS}$  latency = 2, burst length = 4
- 2. A8, A9, and A11 = "Don't Care"



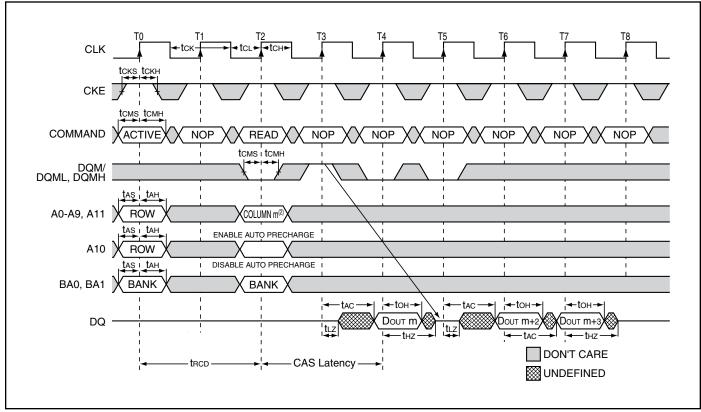
# **READ - FULL-PAGE BURST**



- 1.  $\overline{CAS}$  latency = 2, burst length = full page
- 2. A8, A9, and A11 = "Don't Care"



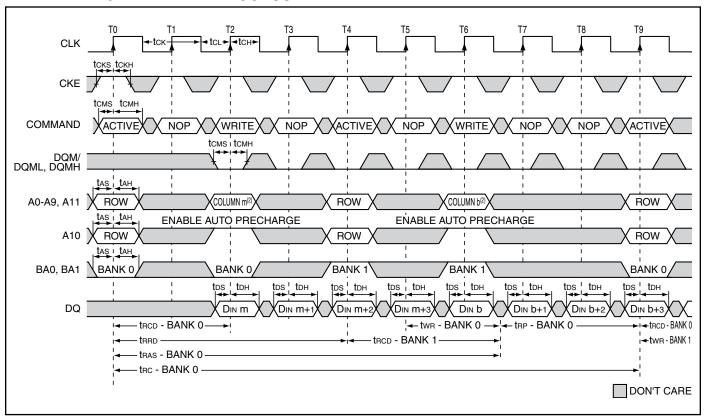
# **READ - DQM OPERATION**



- 1.  $\overline{CAS}$  latency = 2, burst length = 4
- 2. A8, A9, and A11 = "Don't Care"



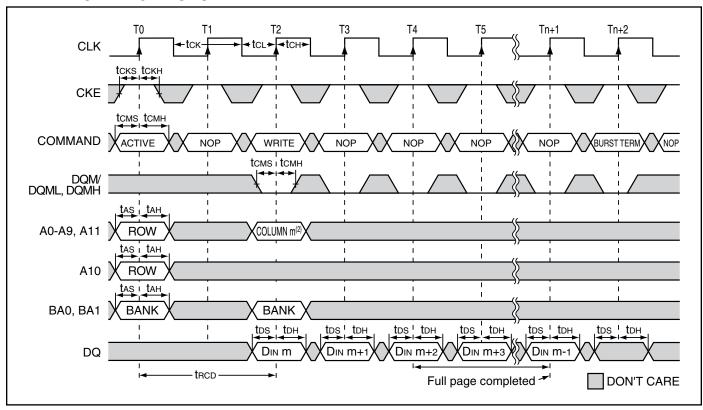
#### **ALTERNATING BANK WRITE ACCESS**



- 1. burst length = 4
- 2. A8, A9, and A11 = "Don't Care"



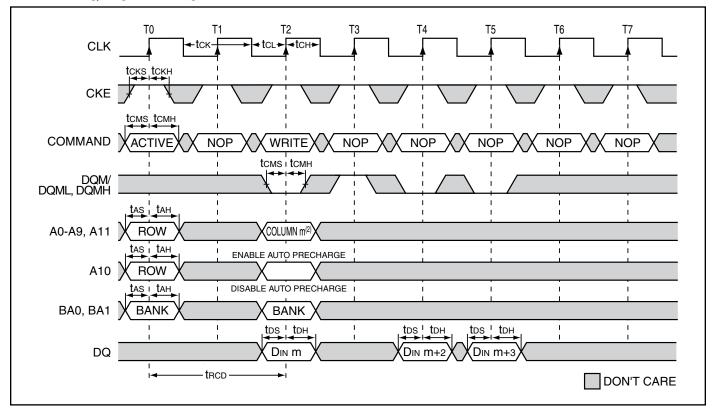
# **WRITE - FULL PAGE BURST**



- 1. burst length = full page
- 2. A8, A9, and A11 = "Don't Care"



# **WRITE - DQM OPERATION**



- 1. burst length = 4
- 2. A8, A9, and A11 = "Don't Care"



## **ORDERING INFORMATION**

Commercial Range: 0°C to 70°C

Frequency	Speed (ns)	Order Part No.	Package
200 MHz	5	IS42S16400J-5TL IS42S16400J-5BL	54-Pin TSOPII, Alloy42 leadframe plated with matte Sn 54-ball BGA, SnAgCu balls
166 MHz	6	IS42S16400J-6TL IS42S16400J-6BL	54-Pin TSOPII, Alloy42 leadframe plated with matte Sn 54-ball BGA, SnAgCu balls
143 MHz	7	IS42S16400J-7TL IS42S16400J-7BL	54-Pin TSOPII, Alloy42 leadframe plated with matte Sn 54-ball BGA, SnAgCu balls

# Industrial Range: -40°C to 85°C

Frequency	Speed (ns)	Order Part No.	Package
200 MHz	5	IS42S16400J-5BLI	54-ball BGA, SnAgCu balls
166 MHz	6	IS42S16400J-6TLI IS42S16400J-6BLI	54-Pin TSOPII, Alloy42 leadframe plated with matte Sn 54-ball BGA, SnAgCu balls
143 MHz	7	IS42S16400J-7TLI IS42S16400J-7BLI IS42S16400J-7B2LI	54-Pin TSOPII, Alloy42 leadframe plated with matte Sn 54-ball BGA, SnAgCu balls 60-ball BGA, SnAgCu balls

# Automotive Range (A1): -40°C to 85°C

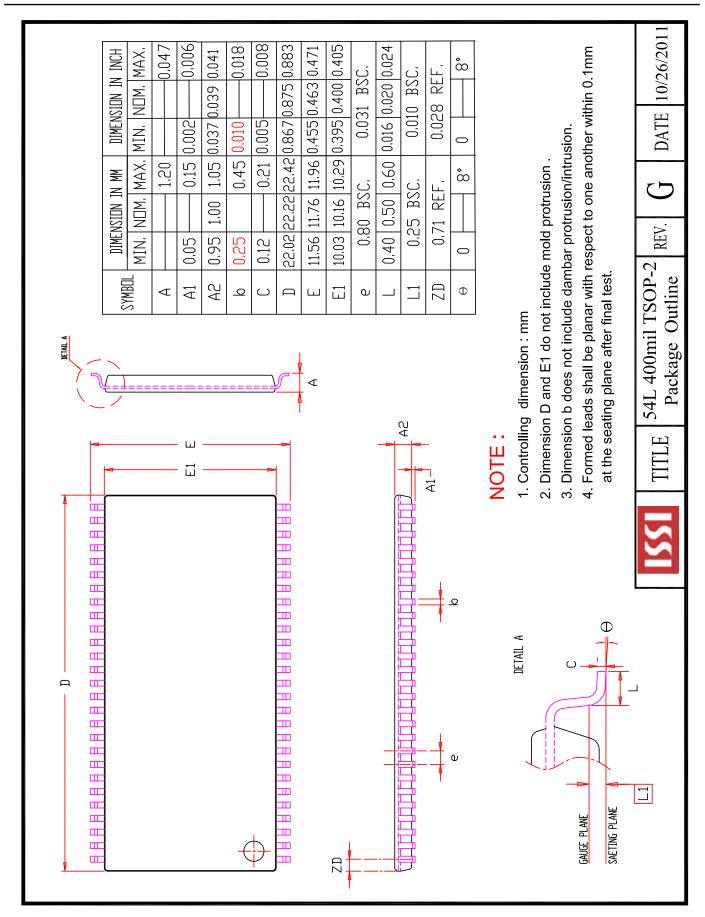
Frequency	Speed (ns)	Order Part No.	Package
200 MHz	5	IS45S16400J-5TLA1 IS45S16400J-5CTLA1 IS45S16400J-5BLA1	54-Pin TSOPII, Alloy42 leadframe plated with matte Sn 54-Pin TSOPII, Cu leadframe plated with matte Sn 54-ball BGA, SnAgCu balls
166 MHz	6	IS45S16400J-6TLA1 IS45S16400J-6CTLA1 IS45S16400J-6BLA1	54-Pin TSOPII, Alloy42 leadframe plated with matte Sn 54-Pin TSOPII, Cu leadframe plated with matte Sn 54-ball BGA, SnAgCu balls
143 MHz	7	IS45S16400J-7TLA1 IS45S16400J-7CTLA1 IS45S16400J-7BLA1	54-Pin TSOPII, Alloy42 leadframe plated with matte Sn 54-Pin TSOPII, Cu leadframe plated with matte Sn 54-ball BGA, SnAgCu balls

# Automotive Range (A2): -40°C to 105°C

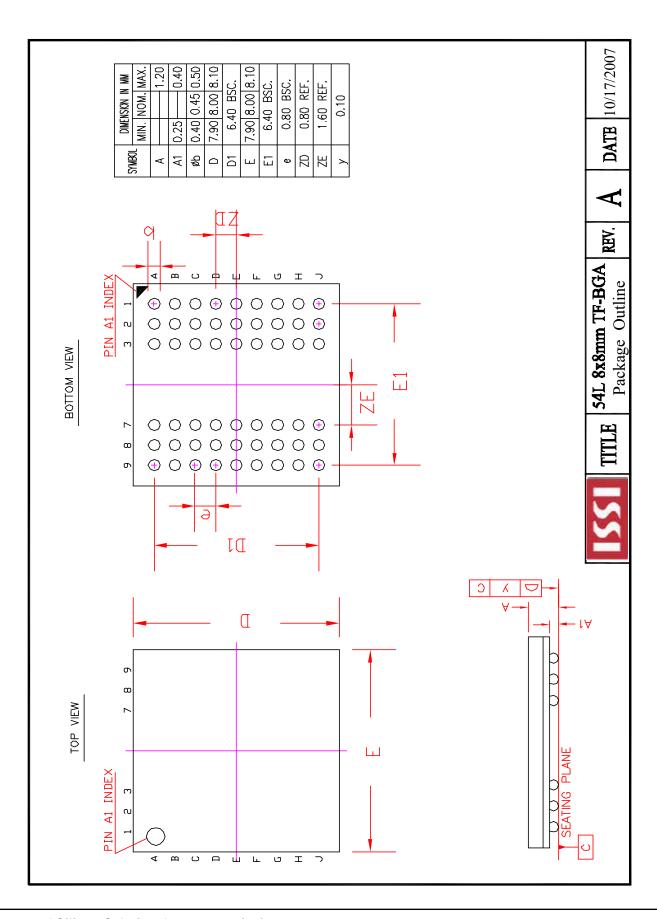
Frequency	Speed (ns)	Order Part No.	Package
166 MHz	6	IS45S16400J-6CTLA2	54-Pin TSOPII, Cu leadframe plated with matte Sn
		IS45S16400J-6BLA2	54-ball BGA, SnAgCu balls
143 MHz	7	IS45S16400J-7TLA2	54-Pin TSOPII, Alloy42 leadframe plated with matte Sn
		IS45S16400J-7CTLA2	54-Pin TSOPII, Cu leadframe plated with matte Sn
		IS45S16400J-7BLA2	54-ball BGA, SnAgCu balls

- 1. Contact ISSI for leaded and copper leadframe parts support.
- 2. Part numbers with "L" or "N" are leadfree, and RoHS compliant.

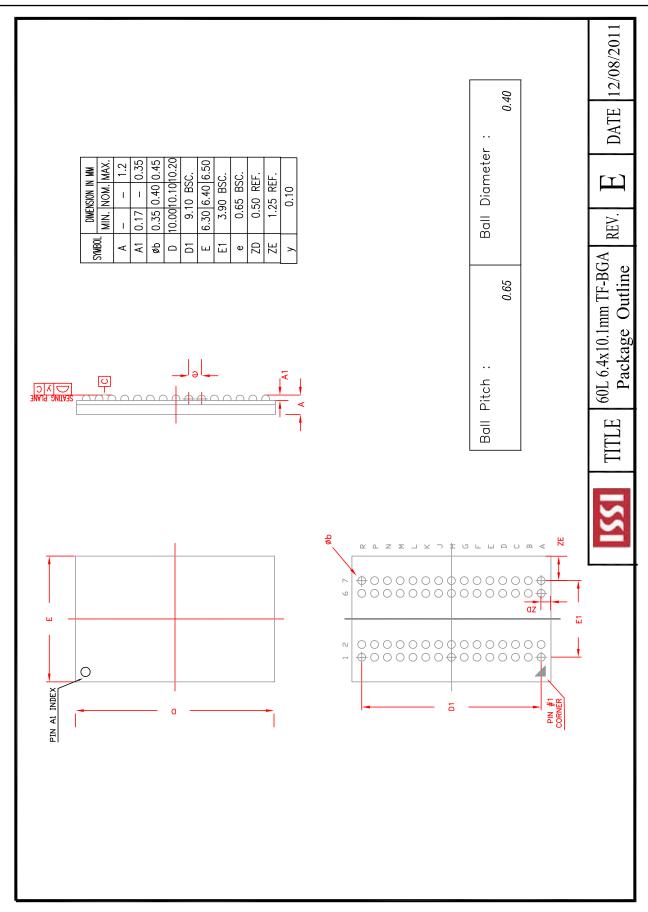












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# ISSI:

IS42S16400J-6TL IS42S16400J-6TL-TR IS42S16400J-6TLI IS42S16400J-6TLI-TR IS42S16400J-7TL
IS42S16400J-7TL-TR IS42S16400J-7TLI IS42S16400J-7TLI-TR IS42S16400J-5BL IS42S16400J-5BL-TR
IS42S16400J-5TL IS42S16400J-5TL-TR IS42S16400J-6BL IS42S16400J-6BLI IS42S16400J-6BLI-TR
IS42S16400J-6BL-TR IS42S16400J-7BL IS42S16400J-7BLI IS42S16400J-7BLI-TR IS42S16400J-7BL-TR
IS45S16400J-6BLA2 IS45S16400J-6BLA1 IS45S16400J-6TLA1 IS45S16400J-6BLA1-TR IS45S16400J-6TLA2-TR
IS45S16400J-6TLA1-TR IS45S16400J-6TLA2 IS45S16400J-6BLA2-TR IS45S16400J-6CTLA1-TR IS45S16400J-7BLA1 IS45S16400J-7TLA1-TR IS45S16400J-7TLA2-TR
IS45S16400J-7TLA1 IS45S16400J-7BLA1-TR IS45S16400J-7CTLA2 IS45S16400J-7B2LI-TR IS45S16400J-7BLA2-TR
IS45S16400J-6CTLA1 IS45S16400J-7B2LI IS45S16400J-7CTLA2 IS42S16400J-7B2LI-TR IS45S16400J-7BLA2-TR